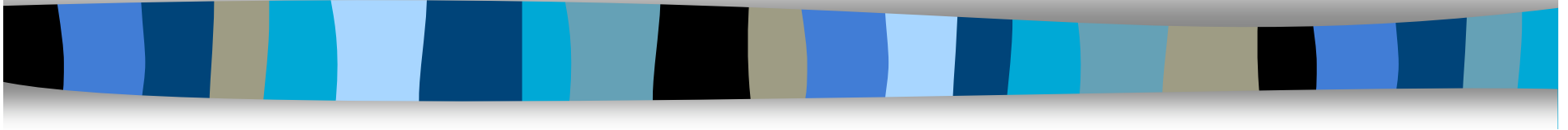


Chapter 22 - Alternating Current



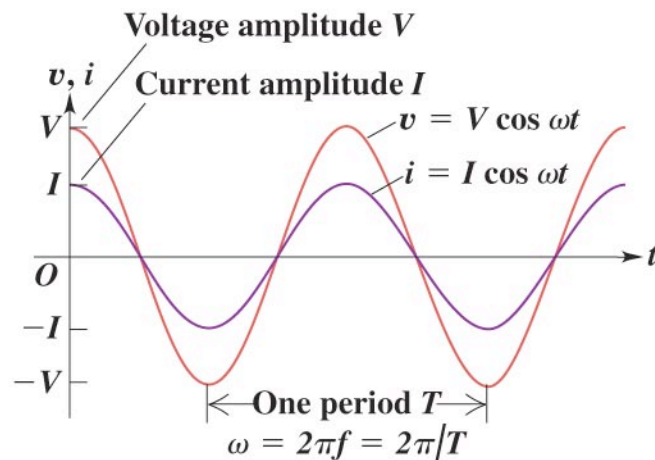


reading quiz

- which of the following is the correct relationship between peak voltage(V) and rms voltage(V_{rms}):
 - A. $V = V_{\text{rms}} \sqrt{2}$
 - B. $V = V_{\text{rms}} / \sqrt{2}$
 - C. $V = \sqrt{2V_{\text{rms}}}$
 - D. $V = \sqrt{V_{\text{rms}}/2}$
- The reactance of a capacitor is
 - A. proportional to the ac frequency
 - B. inversely proportional to the ac frequency
 - C. independent of the ac frequency
 - D. always zero

alternating current

- thus far we've mainly dealt with circuits under **direct current** conditions - that is where the supplied voltage or current does not change with time
- another common situation is where the voltage and current varies with time in a **sinusoidal** way

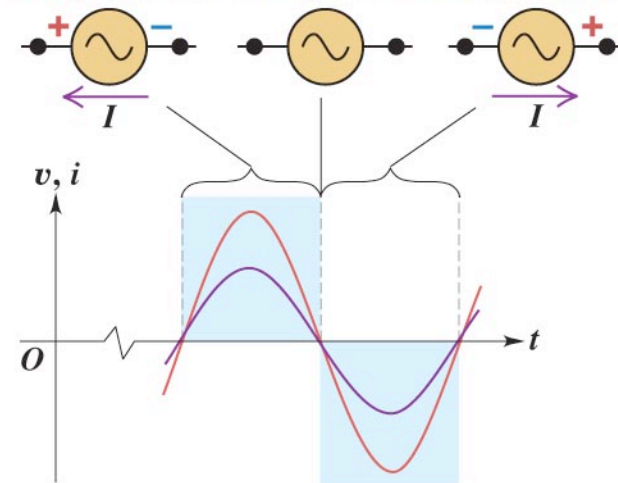


(a) Graphs of sinusoidal current and voltage versus time. The relative heights of the two curves are not significant.

$$v = V \cos \omega t$$

$$i = I \cos \omega t$$

Current and voltage positive Current and voltage zero Current and voltage negative



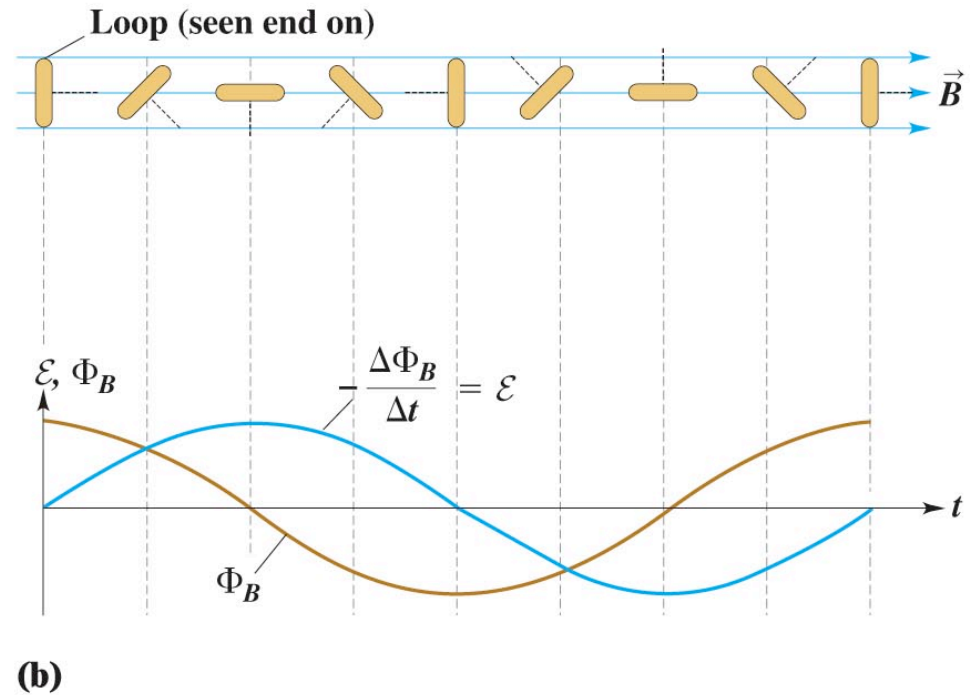
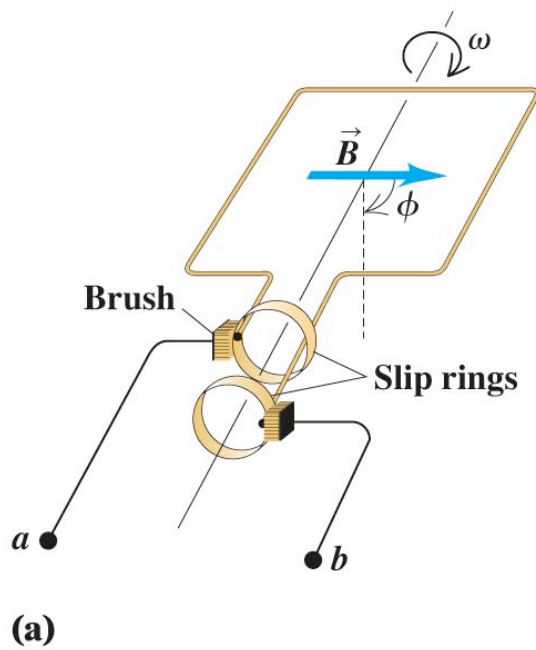
(b) The graphs related to a schematic ac source.

V = peak voltage

I = peak current

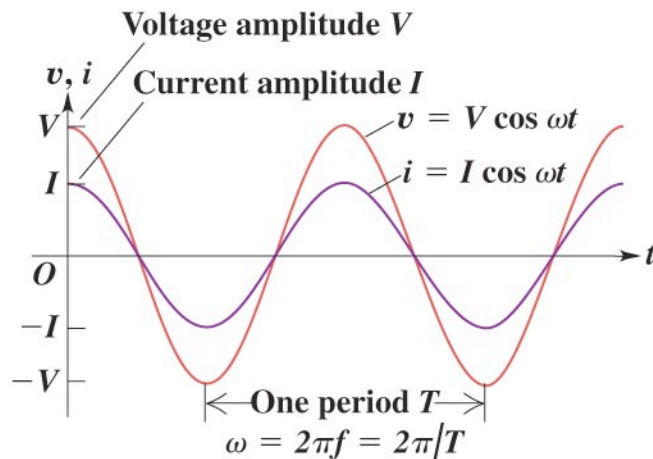
producing alternating current

- we saw one way last time



phasors

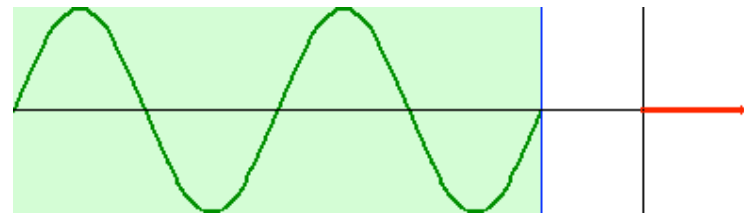
- one way to visualise sinusoidal behaviour (if you don't like graphs) is to use a '**phasor**'
- this is a vector that rotates at a fixed angular velocity



(a) Graphs of sinusoidal current and voltage versus time. The relative heights of the two curves are not significant.

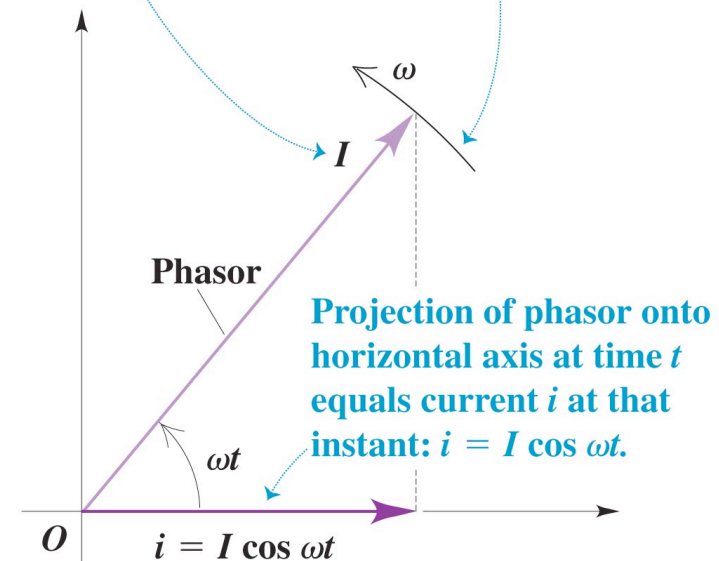
$$v = V \cos \omega t$$

$$i = I \cos \omega t$$



Length of phasor equals maximum current I .

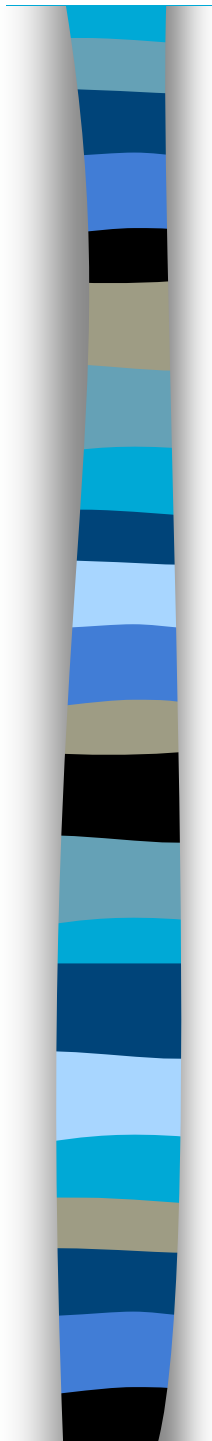
Phasor rotates with frequency f and angular speed $\omega = 2\pi f$.



alternating current

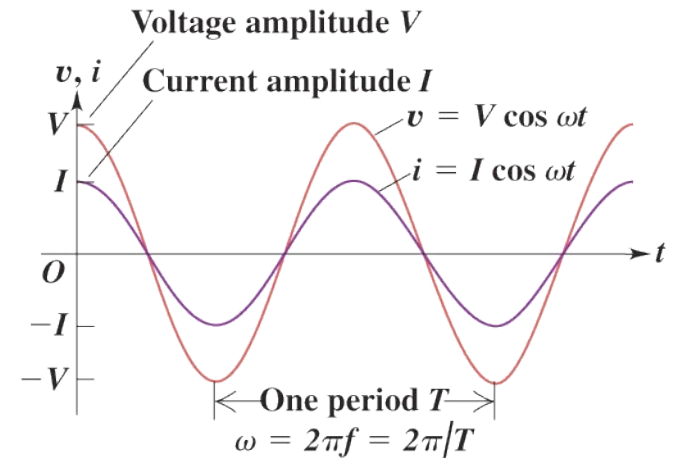
$$\omega = 2\pi f$$

- the current in a circuit behaves like $i = I \cos \omega t$, with a frequency $f = 1$ Hz. At $t=0$, the current is measured to be 1.0 A. What is the current 0.5 s later?
 - A. 1.0 A
 - B. -1.0 A
 - C. 0.0 A
 - D. 0.5 A
- what is the current at $t=0.75$ s ?
 - A. 1.0 A
 - B. -1.0 A
 - C. 0.0 A
 - D. 0.5 A



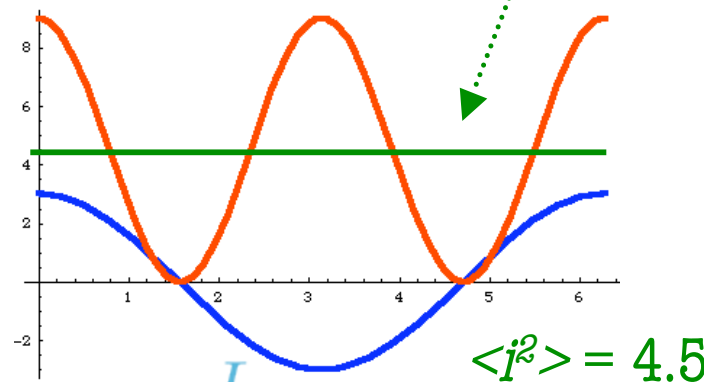
root-mean-square

- notice that the simple average current is zero
- over a full cycle i is negative as much as positive
- a more useful average is the **root-mean-square**, or **rms**
- defined to be the **square root** of the **average** of the **squared current**



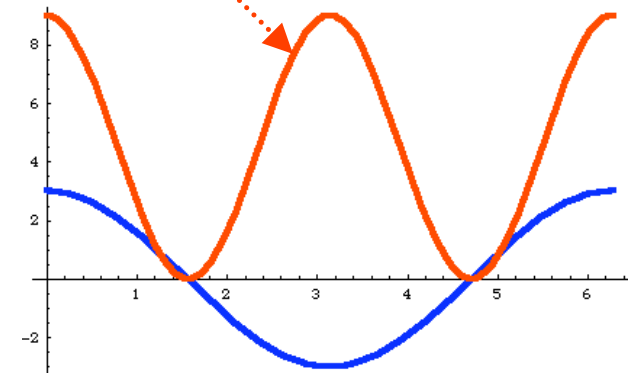
(a) Graphs of sinusoidal current and voltage versus time. The relative heights of the two curves are not significant.

$$\sqrt{\langle i^2 \rangle} = 2.12$$



in general

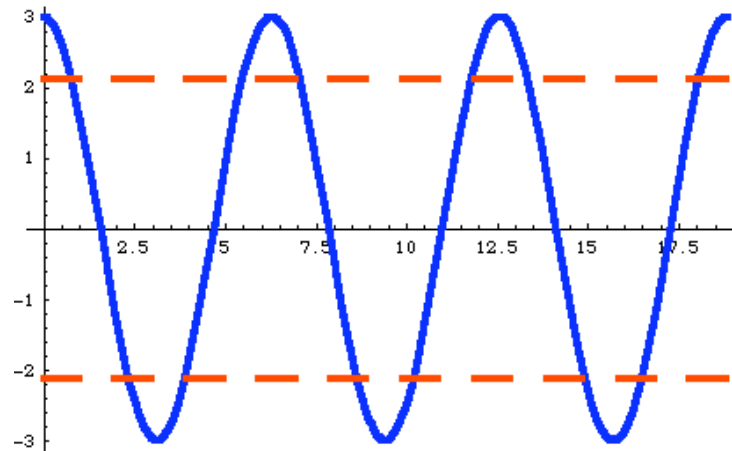
$$I_{\text{rms}} = \frac{I}{\sqrt{2}}$$



$$I = 3$$

root-mean-square

- rms current and voltage is what is usually quoted as the current and voltage of an ac system
- e.g. the 120V household supply in the US is $V_{\text{rms}} = 120 \text{ V}$
- the peak is $V = 120 \text{ V} * \sqrt{2} = 170 \text{ V}$
- good 'average description'



alternating current circuits

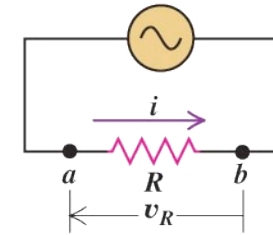
- how do simple circuits behave if we put alternating current through them?

- **circuit with a resistor**, Ohm's law describes the voltage drop across the resistor in terms of the current

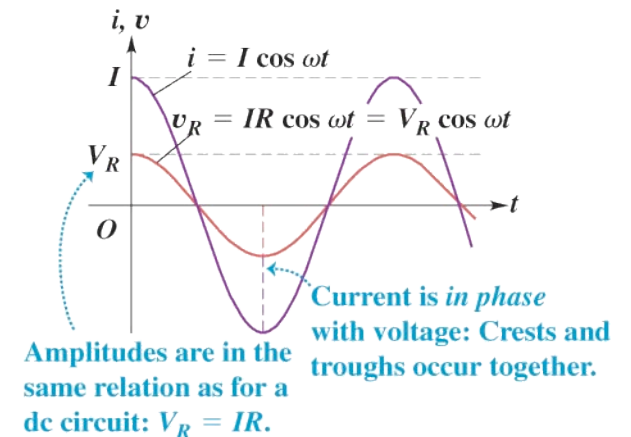
$$v_R = iR$$

$$v_R = IR \cos \omega t$$

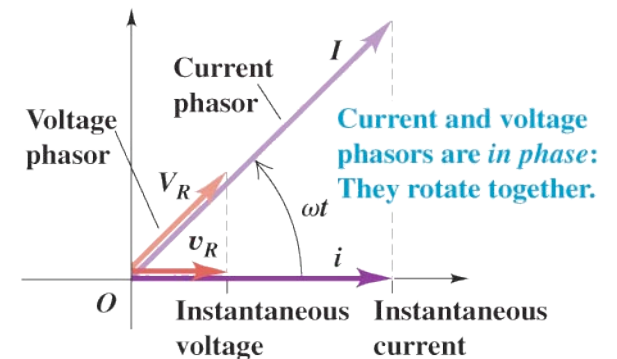
- time-dependence of voltage is the same as the current
 - "phasors stay in-step"



(a) Circuit with ac source and resistor



(b) Graphs of current and voltage versus time



(c) Phasor diagram

inductor

- **circuit with an inductor**, recall the version of Faraday's law for self-inductance

$$v_L = L \frac{\Delta i}{\Delta t}$$

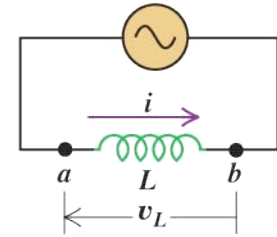
- so the voltage is proportional to the **slope** of the current-time graph

- current slope is biggest when $i=0$ and smallest when $i=I$
- voltage peaks one quarter of a cycle earlier than the current
- "voltage leads current by $90^\circ = \pi/2$ rads"

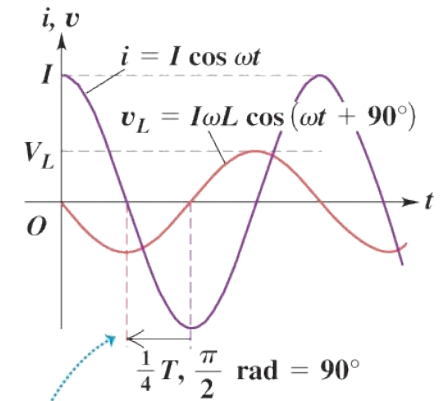
$$v_L = -I\omega L \sin(\omega t)$$

$$v_L = -I\omega L \cos(\omega t + \pi/2)$$

" inductive reactance $\mathbf{X_L} = \omega\mathbf{L}$ "



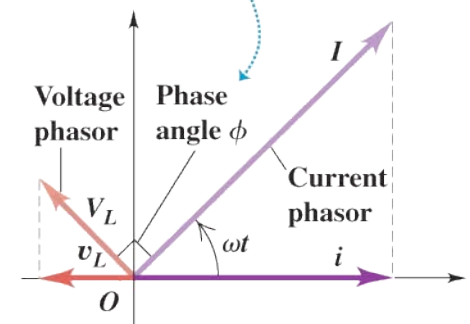
(a) Circuit with ac source and inductor



Voltage curve leads current curve by a quarter cycle (corresponding to $\phi = \pi/2$ rad = 90°).

(b) Graphs of current and voltage versus time

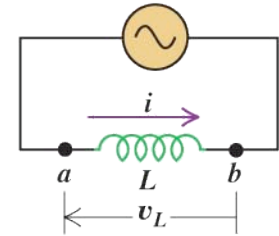
Voltage phasor leads current phasor by $\phi = \pi/2$ rad = 90° .



(c) Phasor diagram

inductor

“ inductive reactance $X_L = \omega L$ ”



(a) Circuit with ac source and inductor

so the peak (or rms) voltage across the inductor can be written

$$V_L = I X_L$$

which looks like Ohm's law with reactance in place of resistance

- high frequency current signals will have a higher reactance and hence cause smaller voltages across the inductor
 - *inductors “choke” off high frequency signals*

capacitor

- **circuit with an capacitor**, recall that the charge on a capacitor is related to the voltage across it

$$v_c = q/C$$

- the rate at which the voltage changes then is related to the rate at which the charge changes, i.e. the current

$$\frac{\Delta v_c}{\Delta t} = \frac{1}{C} \frac{\Delta q}{\Delta t} = \frac{i}{C}$$

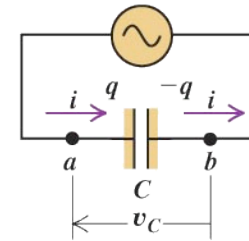
- the only way this can hold true is if

$$v_C = \frac{1}{\omega C} \sin \omega t$$

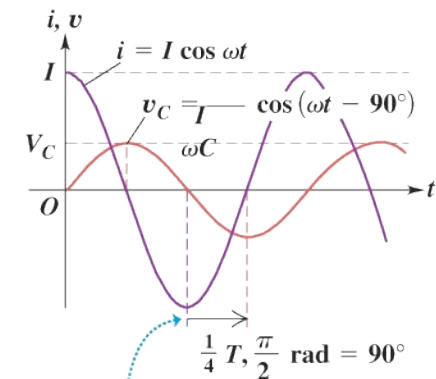
$$v_C = \frac{1}{\omega C} \cos(\omega t - \pi/2)$$

– “voltage lags current by $90^\circ = \pi/2$ rads”

“ capacitive reactance $X_C = 1/(\omega C)$ ”

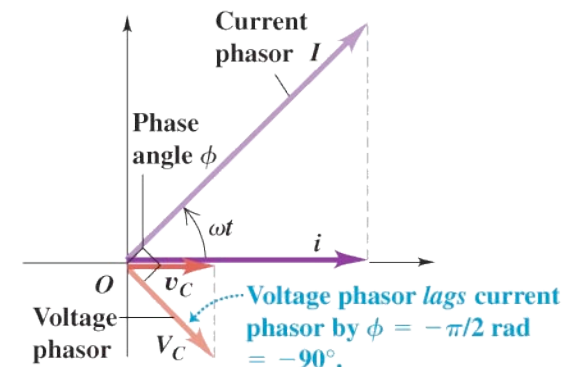


(a) Circuit with ac source and capacitor



Voltage curve lags current curve by a quarter cycle (corresponding to $\phi = \pi/2$ rad = 90°).

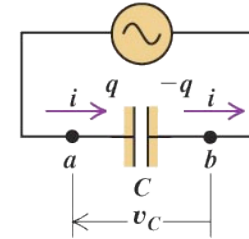
(b) Graphs of current and voltage versus time



(c) Phasor diagram

capacitor

“ capacitive reactance $X_C = 1/(\omega C)$ ”



(a) Circuit with ac source and capacitor

so the peak (or rms) voltage across the capacitor can be written

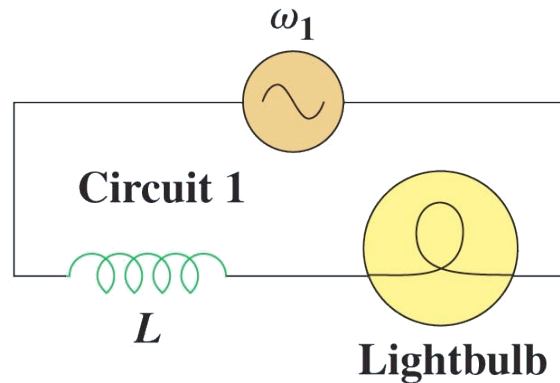
$$V_C = I X_C$$

which looks like Ohm's law with reactance in place of resistance

- low frequency current signals will have a higher reactance and hence cause smaller voltages across the capacitor
 - *capacitors block low frequency currents*

reactance & current

$$X_C = 1/(\omega C)$$
$$X_L = \omega L$$
$$V = I X$$



keeping the source voltage constant we **reduce** the angular frequency ω_1

what happens to the brightness of the bulb:

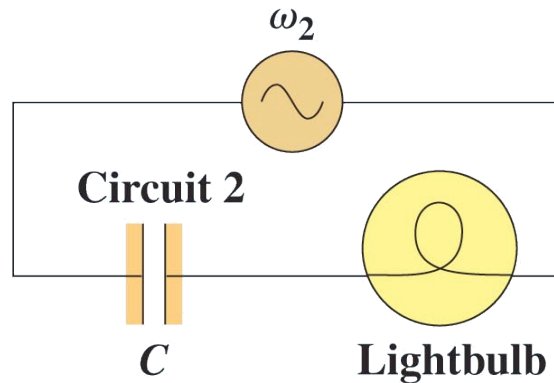
- A. gets dimmer
- B. gets brighter
- C. stays the same

reactance & current

$$X_C = 1/(\omega C)$$

$$X_L = \omega L$$

$$V = I X$$

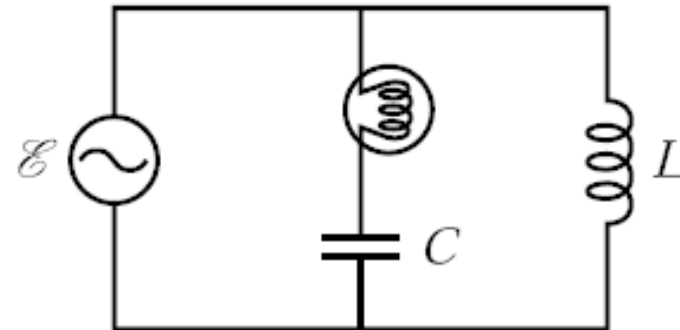


keeping the source voltage constant we **reduce** the angular frequency ω_2

what happens to the brightness of the bulb:

- A. gets dimmer
- B. gets brighter
- C. stays the same

The light bulb has a resistance R , and the emf drives the circuit with a frequency ω . The light bulb glows most brightly at



1. very low frequencies.
2. very high frequencies.
3. the frequency $\omega = 1/\sqrt{LC}$.

$$X_C = 1/(\omega C)$$

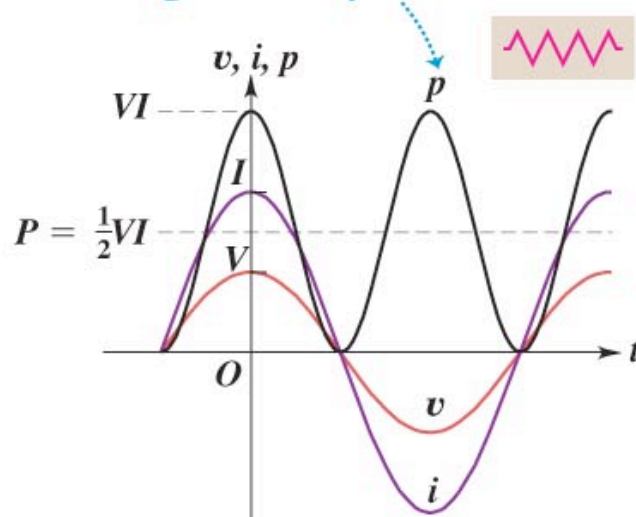
$$X_L = \omega L$$

$$V = I X$$

power in ac circuits

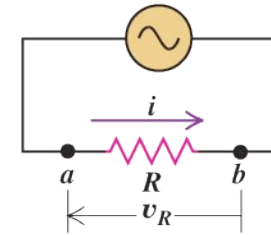
- **circuit with a resistor**
- the instantaneous power supplied by the voltage source $p = v i$

For a resistor, $p = vi$ is always positive because v and i are either both positive or both negative at any instant.

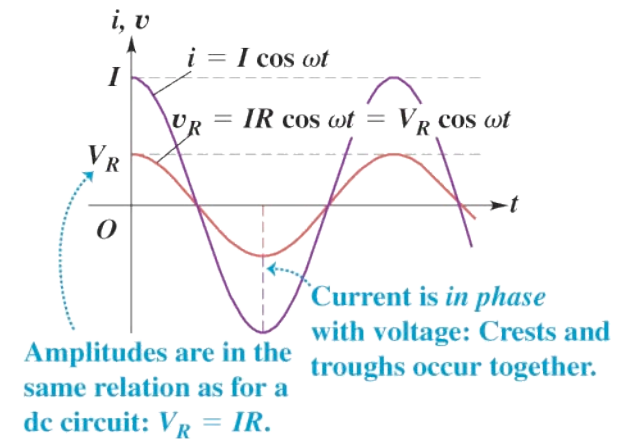


(a) Pure resistor

- average power $P = VI/2 = V_{\text{rms}} I_{\text{rms}} = (I_{\text{rms}})^2 R$



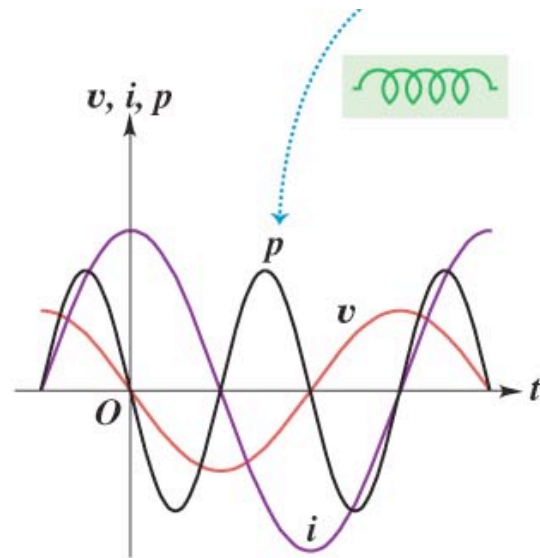
(a) Circuit with ac source and resistor



(b) Graphs of current and voltage versus time

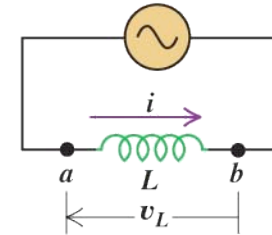
power in ac circuits

- **circuit with an inductor**
- the instantaneous power supplied by the voltage source $p = v i$

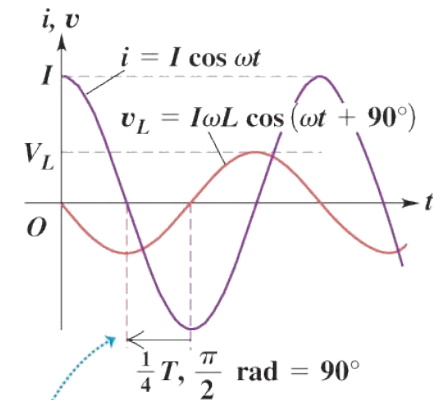


(b) Pure inductor

- voltage leads by a quarter cycle
- average power $P = 0!$



(a) Circuit with ac source and inductor

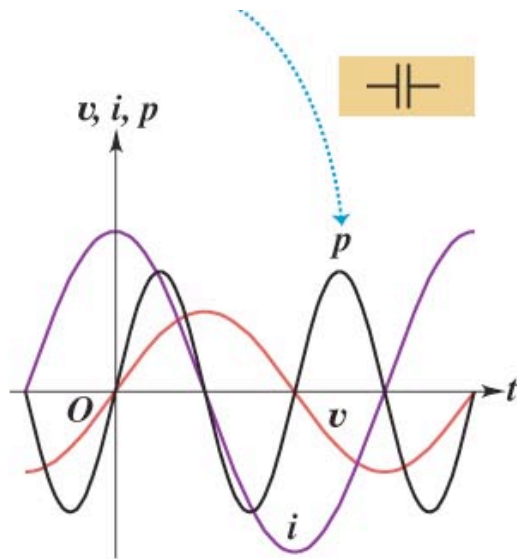


Voltage curve *leads* current curve by a quarter cycle (corresponding to $\phi = \pi/2 \text{ rad} = 90^\circ$).

(b) Graphs of current and voltage versus time

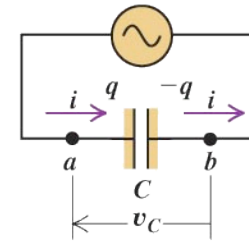
power in ac circuits

- **circuit with a capacitor**
- the instantaneous power supplied by the voltage source $p = v i$

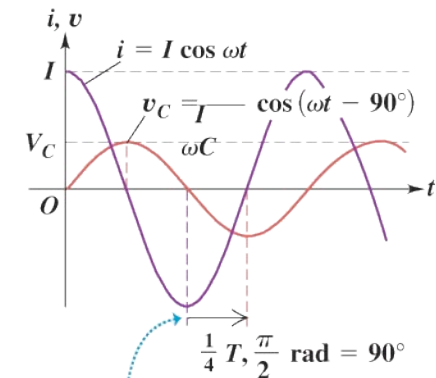


(c) Pure capacitor

- voltage lags by a quarter cycle
- average power $P = 0!$



(a) Circuit with ac source and capacitor

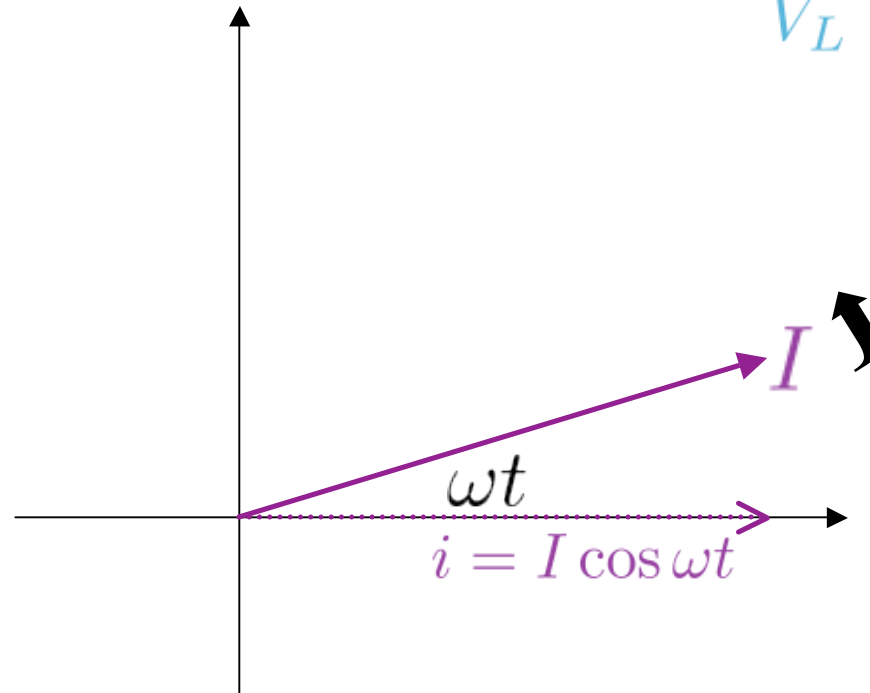
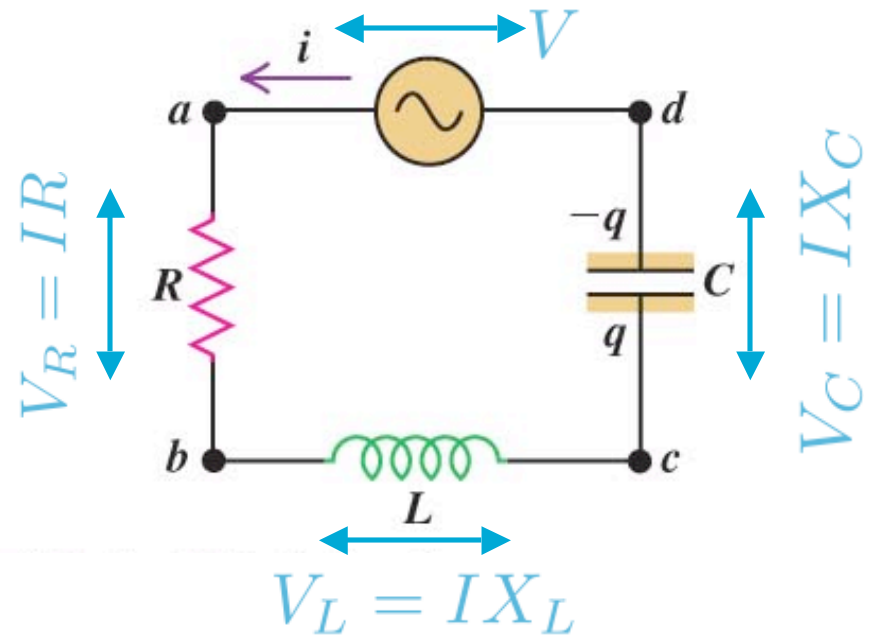


Voltage curve lags current curve by a quarter cycle (corresponding to $\phi = \pi/2 \text{ rad} = 90^\circ$).

(b) Graphs of current and voltage versus time

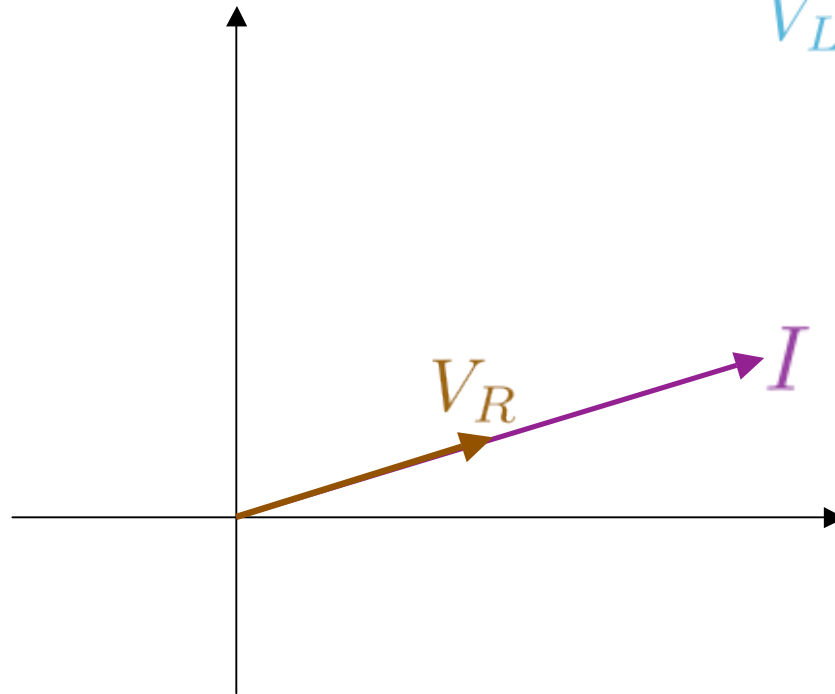
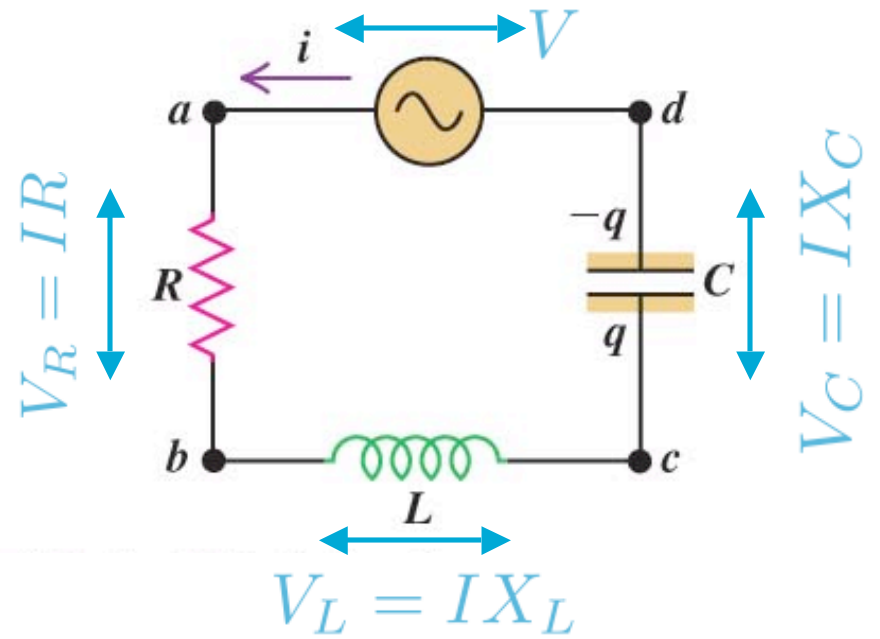
series RLC

- $V = V_R + V_C + V_L$
- these are time-varying voltages we should add the phasors - just like adding vectors



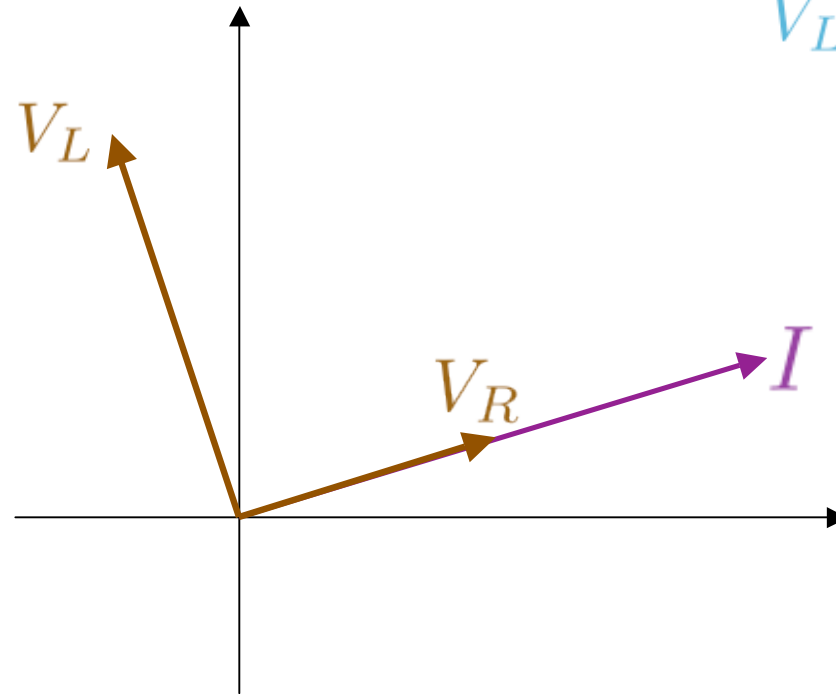
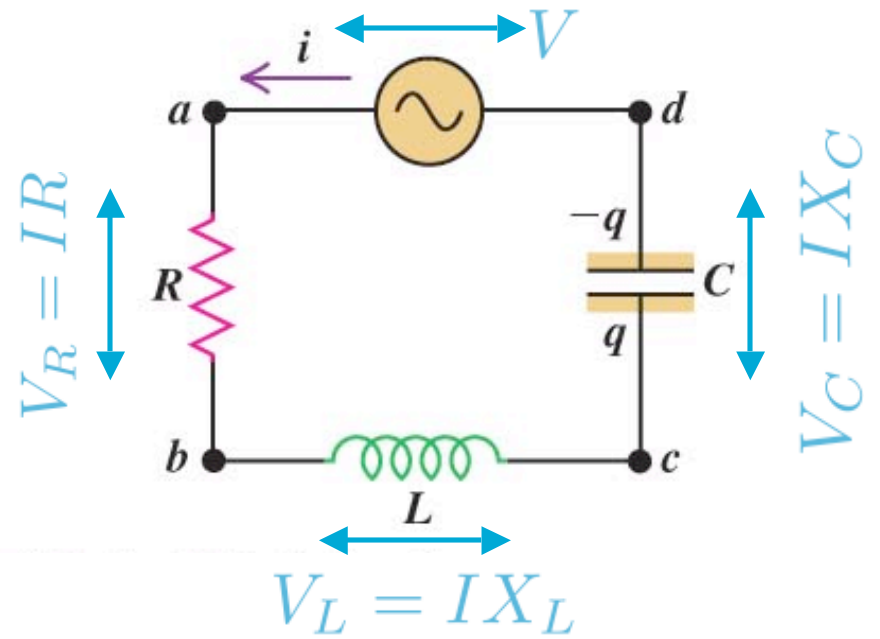
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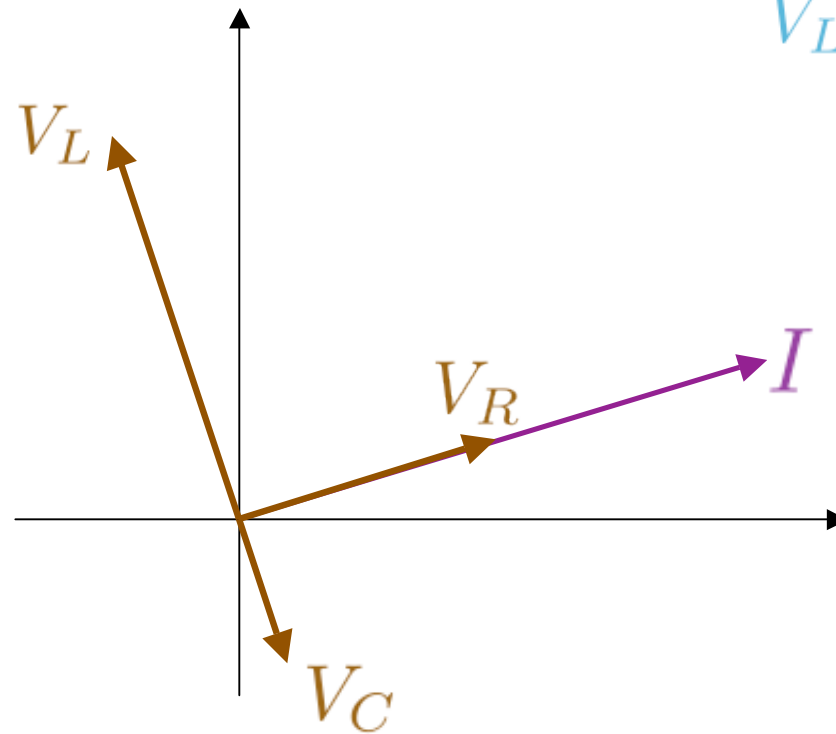
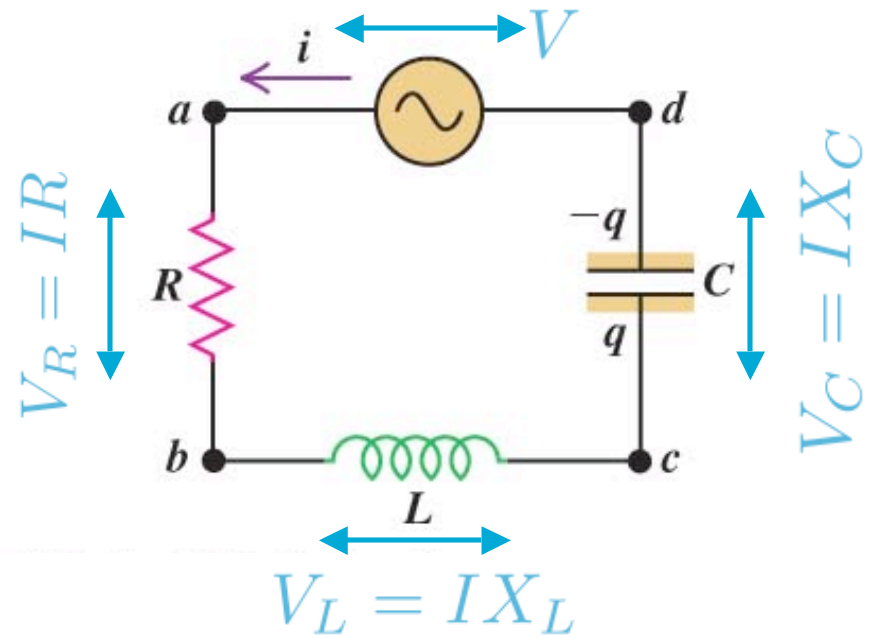
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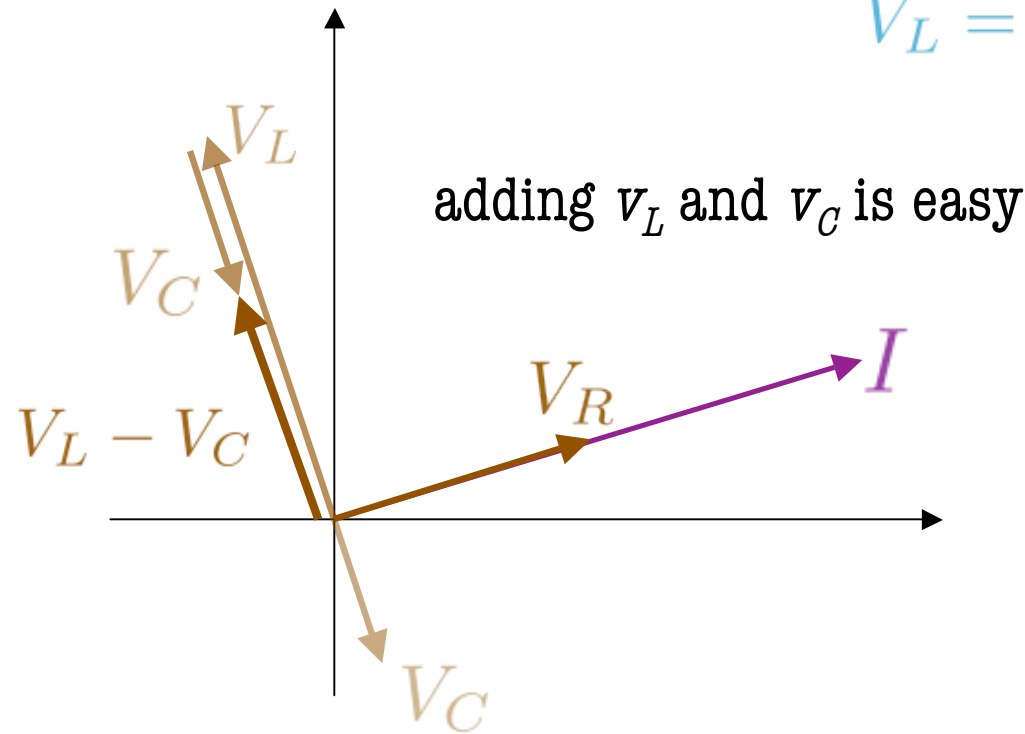
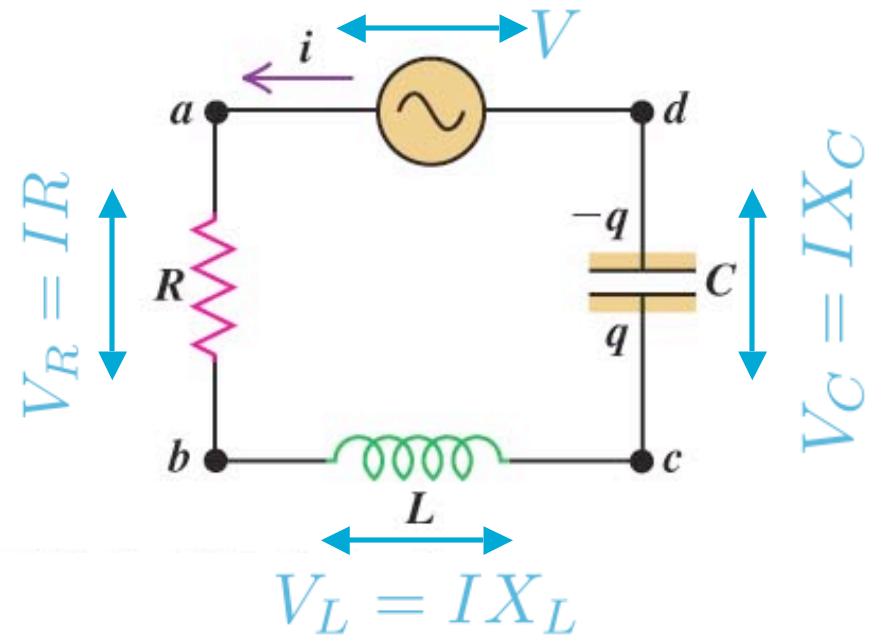
series RLC

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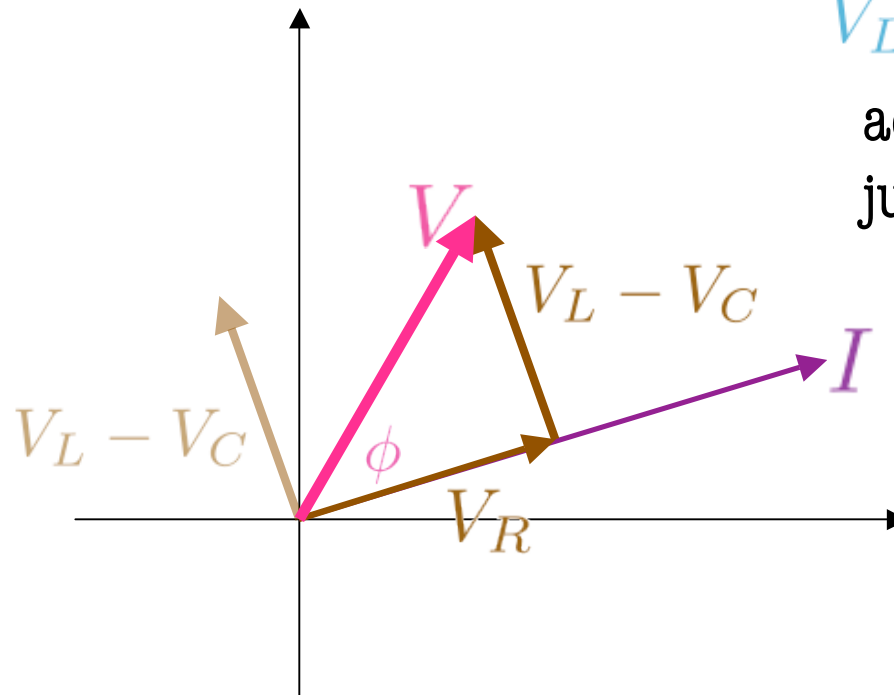
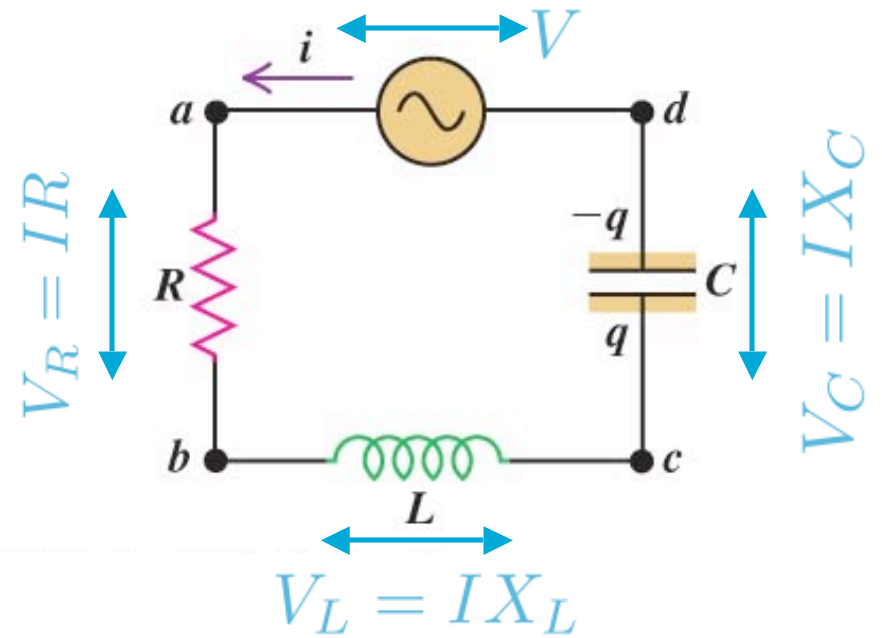
series RLC

- $V = V_R + V_C + V_L$
- these are time-varying voltages we should add the phasors just like adding vectors



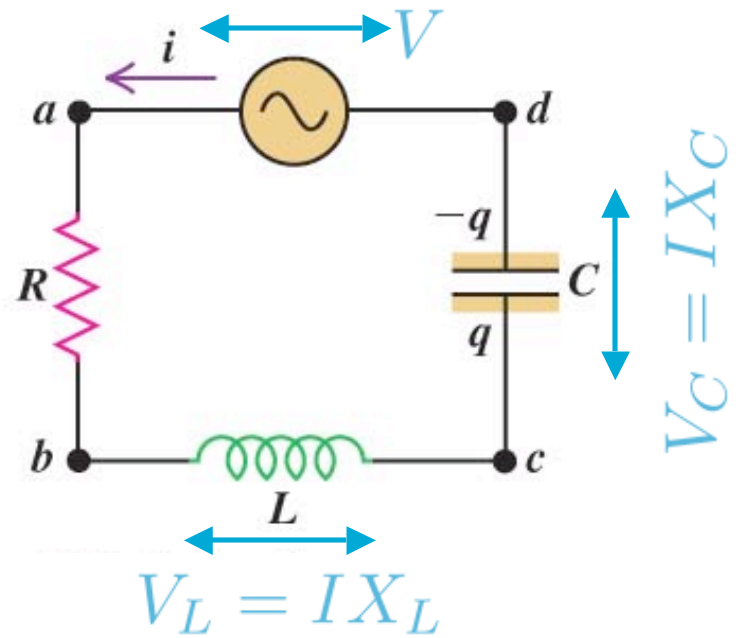
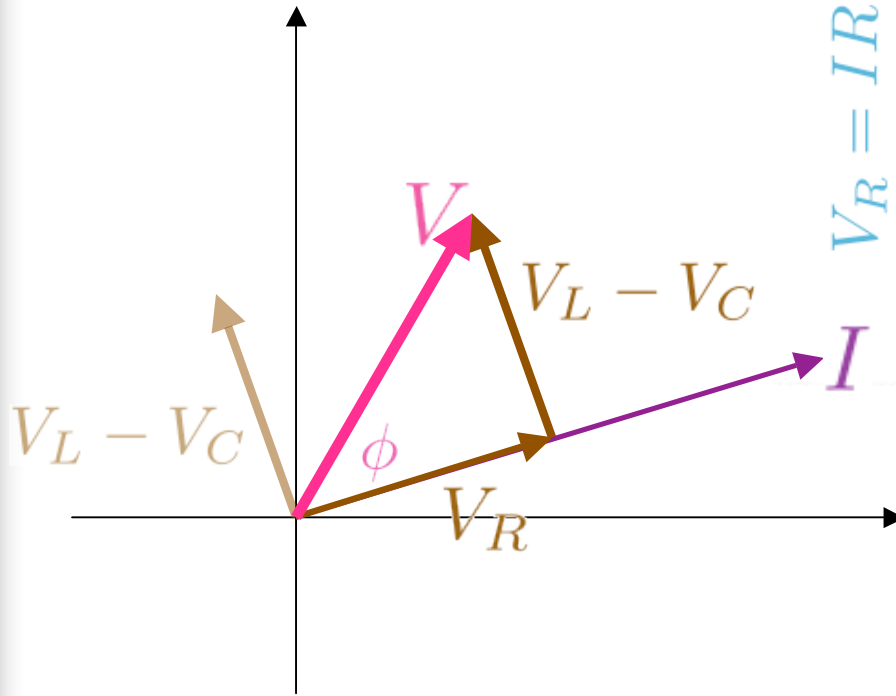
series RLC

- $V = V_R + V_C + V_L$
- these are time-varying voltages we should add the phasors just like adding vectors



adding $v_L + v_C$ to v_R is just adding vectors

series RLC



we define the **impedance** of the circuit to be $Z=V/I$

by pythagoras $V = \sqrt{V_R^2 + (V_L - V_C)^2}$

so $Z = \sqrt{R^2 + (\omega L - \frac{1}{\omega C})^2}$

the phase lag is given by

$$\tan \phi = \frac{\omega L - \frac{1}{\omega C}}{R}$$

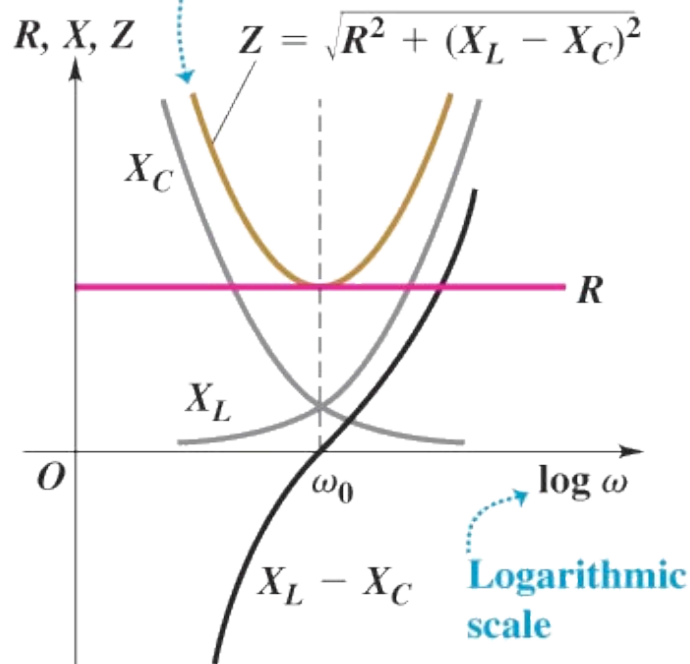
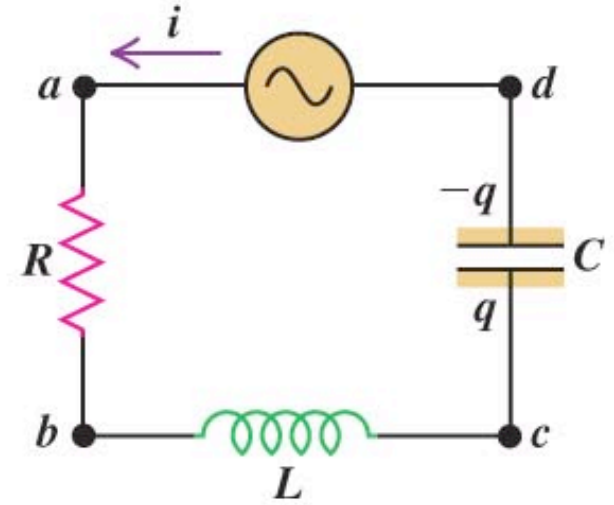
resonant RLC circuit

$$Z = \sqrt{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2}$$

takes its smallest possible value ($Z=R$) if

$$\omega L = \frac{1}{\omega C} \qquad \omega_0 = \frac{1}{\sqrt{LC}}$$

Impedance Z is least at the angular frequency at which $X_C = X_L$.



for a fixed V , the peak current is maximised when Z is minimised

