

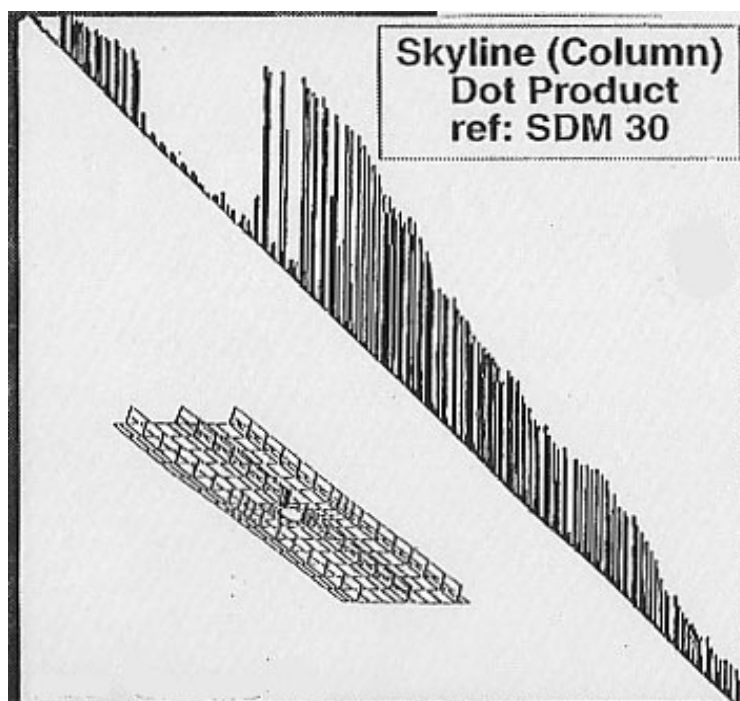
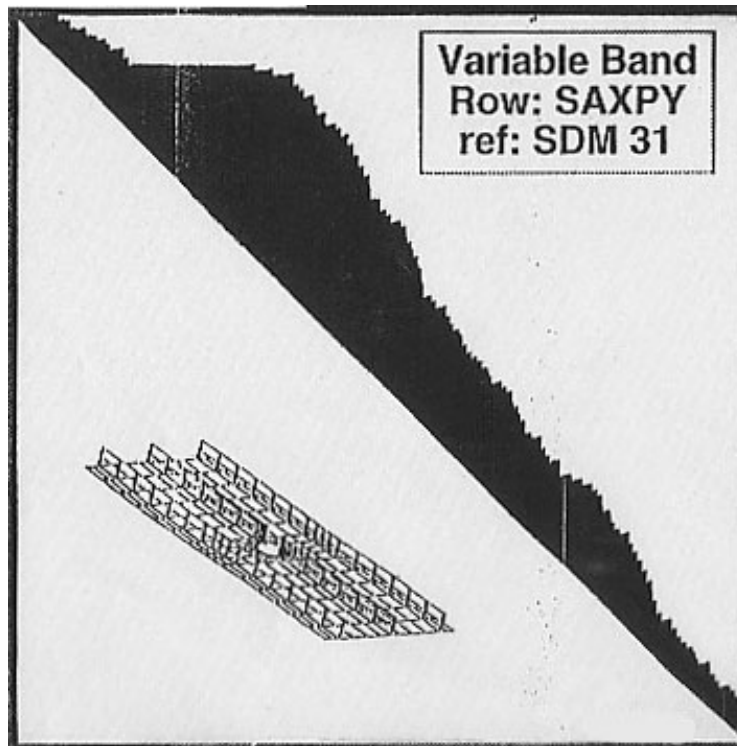
$$[s] = \begin{bmatrix} S_{11} & S_{12} & 0 & S_{14} & 0 & 0 & 0 & 0 & 0 \\ & S_{22} & S_{23} & 0 & 0 & 0 & 0 & 0 & 0 \\ & & S_{33} & S_{34} & 0 & S_{36} & 0 & 0 & 0 \\ & & & S_{44} & S_{45} & S_{46} & 0 & 0 & 0 \\ & & & & S_{55} & S_{56} & 0 & S_{58} & 0 \\ & \text{sym.} & & & & S_{66} & S_{67} & 0 & S_{69} \\ & & & & & & S_{77} & S_{78} & 0 \\ & & & & & & & S_{88} & S_{89} \\ & & & & & & & & S_{99} \end{bmatrix}$$

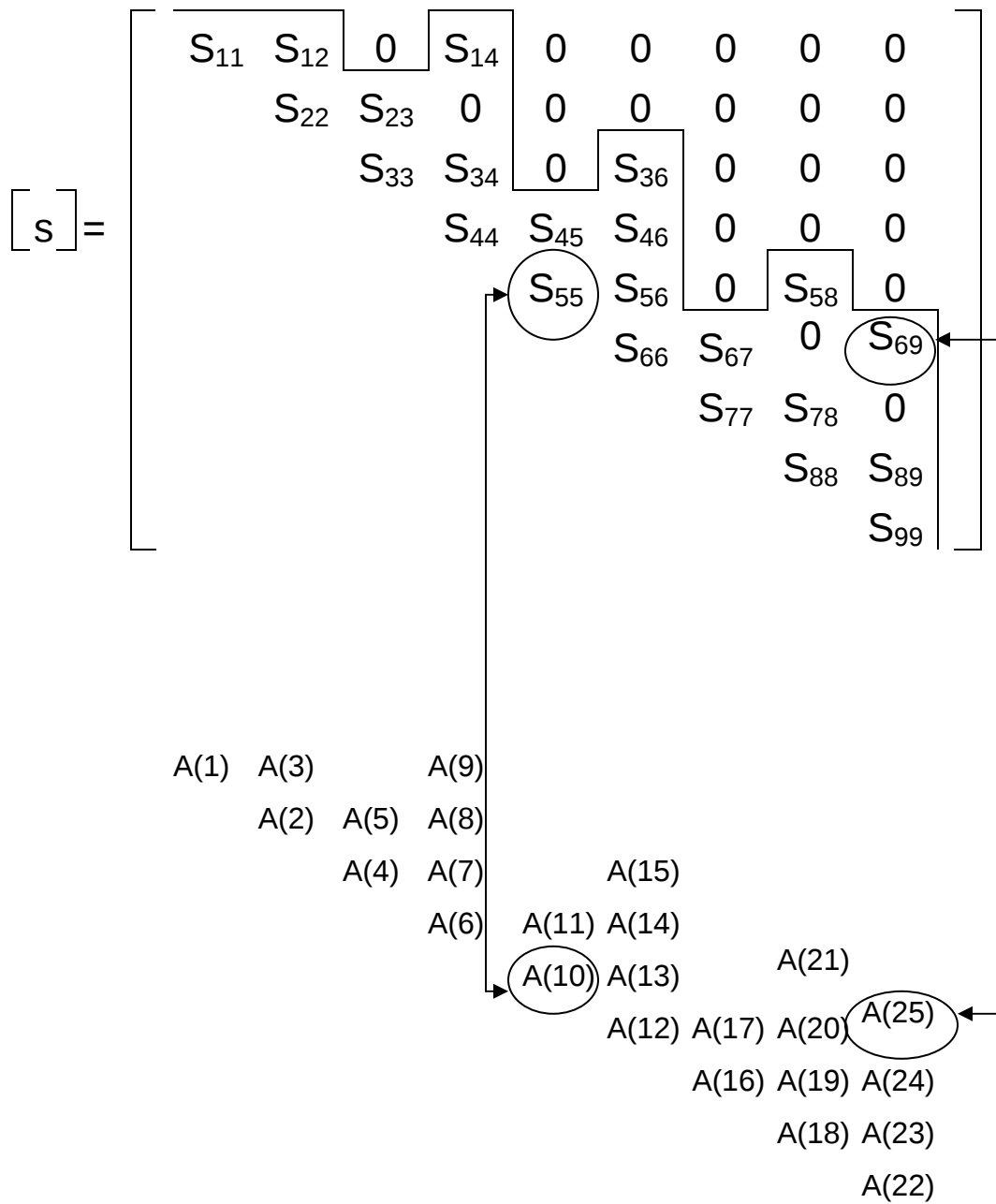
STORAGE SCHEMES :

- FULL 81 WORDS
- SYMMETRIC 45 WORDS
- BANDED 36 WORDS
- VARIABLE BAND 28 WORDS
- SKYLINE 25 WORDS

SPARSE

Matrix Storage Methods
2910 Equation Stiffness Panel





SKYTLINE STORAGE SCHEME FOR STIFFNESS MATRIX

$$\text{COLH} \quad \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \\ 7 \\ 8 \\ 9 \end{bmatrix} = \begin{Bmatrix} 0 \\ 1 \\ 1 \\ 3 \\ 1 \\ 3 \\ 1 \\ 3 \\ 3 \end{Bmatrix} = \text{Column Height} = \text{"Known"}$$

$$\text{MAXA} \quad \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \\ 7 \\ 8 \\ 9 \\ 10=N+1 \end{bmatrix} = \begin{Bmatrix} 1 \\ 2 \\ 4 \\ 6 \\ 10 \\ 12 \\ 16 \\ 18 \\ 22 \\ 26 \end{Bmatrix} = \text{Location of Diagonal Terms}$$

$$\text{MAXA}(1) = 1$$

ALWAYS !

$$\text{MAXA}(I+1) = \text{MAXA}(I) + \text{COLH}(I) + 1$$

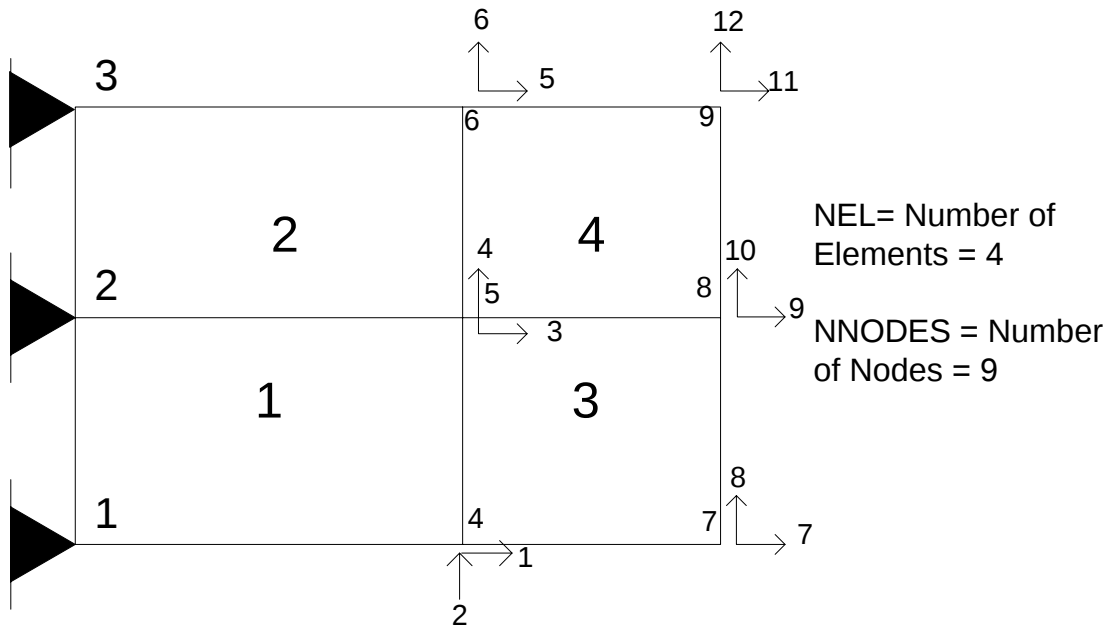
$$\text{THUS:} \quad S_{IJ} = A[\text{MAXA}(J) + J - I]$$

$$\text{Example:} \quad S_{55} = A[\text{MAXA}(5) + 5 - 5] = A[10]$$

$$S_{69} = A[\text{MAXA}(9) + 9 - 6] = A[25]$$

How To Find The Column Height of Each Column

Example:



$$[ID] = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \end{matrix} \\ \begin{matrix} T_x \\ T_y \\ T_z \\ R_x \\ R_y \\ R_z \end{matrix} & \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \end{bmatrix} \end{matrix}$$

Convention :

- 1 If the Degree of Freedom (DOF) is fixed
- 0 If the DOF is free to move

$$[ID] = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ 0 & 0 & 0 & 1 & 3 & 5 & 7 & 9 & 11 \\ 0 & 0 & 0 & 2 & 4 & 6 & 8 & 10 & 12 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{matrix} T_x \\ T_y \\ T_z \\ R_x \\ R_y \\ R_z \end{matrix}$$

The following are element connectivities:

$$LM^{(1)} = \text{nodes } 5, 2, 1, 4 = (3, 4, 0, 0, 0, 0, 1, 2)$$

$$LM^{(2)} = \text{nodes } 6, 3, 2, 5 = (5, 6, 0, 0, 0, 0, 3, 4)$$

$$LM^{(3)} = \text{nodes } 8, 5, 4, 7 = (9, 10, 3, 4, 1, 2, 7, 8)$$

$$LM^{(4)} = \text{nodes } 9, 6, 5, 8 = (11, 12, 5, 6, 3, 4, 9, 10)$$

$$\begin{bmatrix} S \end{bmatrix} =$$

	1	2	3	4	5	6	7	8	9	10	11	12
1	1	1	1	1								
2	1	1	1	1								
3	1	1	1	2	1	2	2	2				
4	1	1	1	2	1	2	2	2				
5			2	2	2	2						
6			2	2	2	2						
7												
8												
9												
10												
11												
12												

Thus, the column height for each column is given as:

$$\text{COLH} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \\ 7 \\ 8 \\ 9 \\ 10 \\ 11 \\ 12 \end{bmatrix} = \left\{ \begin{array}{c} 0 \\ 1 \\ 2 \\ 3 \\ 2 \\ 3 \\ 6 \\ 7 \\ 8 \\ 9 \\ 8 \\ 9 \end{array} \right\}$$

The following is a skeletal Fortran statements to compute the column height of each column:

DO 1 I = 1, NEL

C... For I = 1, the smallest DOF = 1, hence

$$\text{COLH} \begin{pmatrix} 3 \\ 4 \\ 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 3-1 \\ 4-1 \\ 1-1 \\ 2-1 \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \\ 0 \\ 1 \end{pmatrix}$$

C...For element I= 2, the smallest DOF = 3, hence

$$\text{COLH} \begin{pmatrix} 5 \\ 6 \\ 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 5-3 \\ 6-3 \\ 3-3 \\ 4-3 \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \\ \cancel{0} \\ \cancel{1} \end{pmatrix} \begin{matrix} \rightarrow 2 \\ \rightarrow 3 \end{matrix}$$

C...For element I= 3, the smallest DOF = 1, hence

$$\text{COLH} \begin{pmatrix} 9 \\ 10 \\ 3 \\ 4 \\ 1 \\ 2 \\ 7 \\ 8 \end{pmatrix} = \begin{pmatrix} 8 \\ 9 \\ 2 \\ 3 \\ 0 \\ 1 \\ 6 \\ 7 \end{pmatrix}$$

C...For element I= 4, the smallest DOF = 3, hence

$$\text{COLH} \begin{pmatrix} 11 \\ 12 \\ 5 \\ 6 \\ 3 \\ 4 \\ 9 \\ 10 \end{pmatrix} = \begin{pmatrix} 8 \\ 9 \\ 2 \\ 3 \\ \cancel{0} \\ \cancel{1} \\ \cancel{6} \\ \cancel{7} \end{pmatrix} \begin{matrix} \rightarrow 2 \\ \rightarrow 3 \\ \rightarrow 8 \\ \rightarrow 9 \end{matrix}$$

1 continue

SEQUENTIAL CHOLESKI METHOD

$$\begin{bmatrix} S \end{bmatrix} \overset{?}{\{Z\}} = \{F\}$$

Step 1. Factorization

$$\begin{bmatrix} S \end{bmatrix} = \begin{bmatrix} L \end{bmatrix} \begin{bmatrix} U \end{bmatrix} = \begin{bmatrix} U \end{bmatrix}^T \begin{bmatrix} U \end{bmatrix}$$

Hence

$$\begin{bmatrix} U \end{bmatrix}^T \left(\begin{bmatrix} U \end{bmatrix} \{Z\} \right) = \{F\}$$


Step 2. Forward Substitution, Solve For $\{y\}$

$$\begin{bmatrix} U \end{bmatrix}^T \left(\begin{bmatrix} Y \end{bmatrix} \right) = \{F\}$$

Step 3. Backward Substitution, Solve For $\{Z\}$

$$\begin{bmatrix} U \end{bmatrix} \{Z\} = \{Y\}$$

TO FIND FACTORIZED MATRIX [U]

Example

known

$$\begin{bmatrix} S_{11} & S_{12} & S_{13} \\ S_{21} & S_{22} & S_{23} \\ S_{31} & S_{32} & S_{33} \end{bmatrix} = \begin{bmatrix} U_{11} & 0 & 0 \\ U_{12} & U_{22} & 0 \\ U_{13} & U_{23} & U_{33} \end{bmatrix} \begin{bmatrix} U_{11} & U_{12} & U_{13} \\ 0 & U_{22} & U_{23} \\ 0 & 0 & U_{33} \end{bmatrix}$$

Thus:

$S_{11} = U_{11}^2$	$U_{11} = \text{SQRT}(S_{11})$	1 st
$S_{12} = U_{11} U_{12}$	$U_{12} = S_{12} / U_{11}$	2 nd
$S_{13} = U_{11} U_{13}$	$U_{13} = S_{13} / U_{11}$	4 th
$S_{22} = U_{12}^2 + U_{22}^2$	$U_{22} = \text{SQRT}(S_{22} - U_{12}^2)$	3 rd
$S_{23} = U_{12} U_{13} + U_{22} U_{23}$	$U_{23} = (S_{23} - U_{12} U_{13}) / U_{22}$	5 th
$S_{33} = U_{13}^2 + U_{23}^2 + U_{33}^2$	$U_{33} = \text{SQRT}(S_{33} - U_{13}^2 - U_{23}^2)$	6 th

Notes:

[U] overwrite [S] !

Column Oriented Approach

PV- Solve (INCORE Version)

In the sequential Choleski method, a symmetric, Positive definite stiffness matrix, $[K]$, can be decomposed as

$$[K] = [U]^T[U] \quad (1)$$

with the coefficients of the upper-triangular matrix, $[U]$:

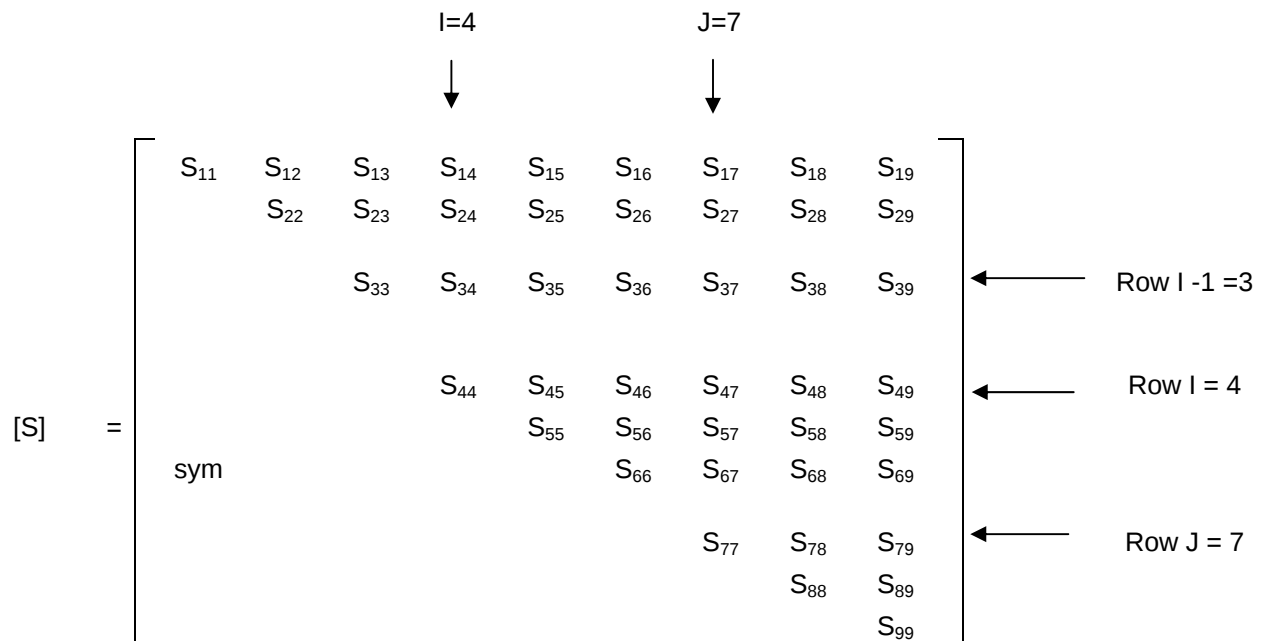
$$U_{ij} = 0 \text{ for } i > j \quad (2)$$

$$u_{11} = \sqrt{K_{11}} \quad u_{1j} = \frac{K_{1j}}{u_{11}} \text{ for } j \geq 1 \quad (3)$$

$$u_{ii} = \sqrt{K_{ii} - \sum_{k=1}^{i-1} (U_{ki})^2} \text{ for } i \geq 1 \quad (4)$$

$$u_{ij} = \frac{K_{ij} - \sum_{k=1}^{i-1} U_{ki} U_{kj}}{U_{ii}} \text{ for } i, j \geq 1 \quad (5)$$

$$u_{57} = \frac{K_{57} - u_{15} \cdot u_{17} - u_{25} \cdot u_{27} - u_{35} \cdot u_{37} - u_{45} \cdot u_{47}}{u_{55}} \quad (8)$$



$$U_{47} = \frac{S_{47} - \sum_{K=1}^{I-1} (U_{14} U_{17} + U_{24} U_{27} + U_{34} U_{37})}{U_{44}}$$

U₇₇ = ?

U₁₁ = SQRT (S₁₁) col #

Do 1 J = 2, n

Do 2 I = Top Row of Col J , Row J

(say J = 7th Column)

(say I = 4th Row)

Do 3 k = Top Row of Col I , Row I - 1

3 Compute $\sum U_{KI} U_{KJ}$

Compute S_{IJ} - $\sum U_{KI} U_{KJ}$

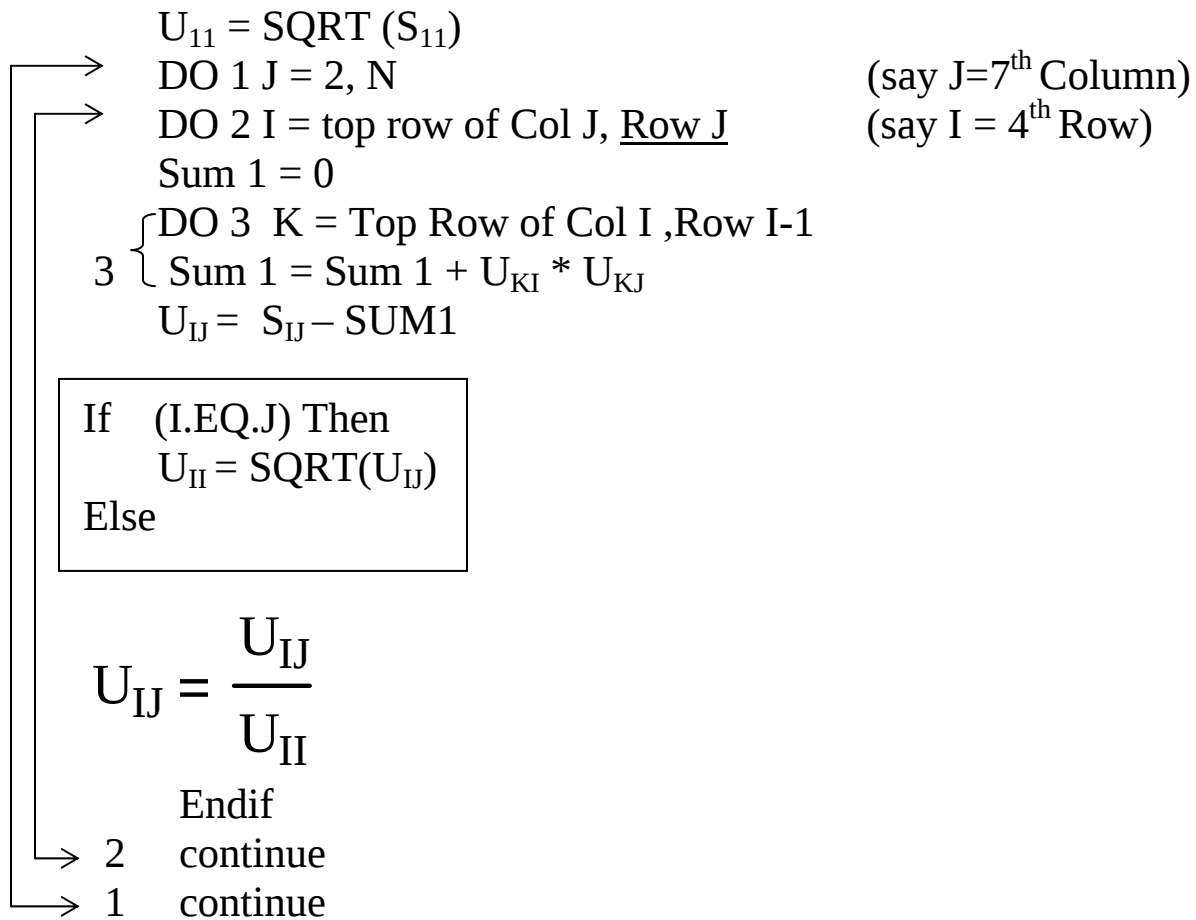
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.

2 continue

1 continue

Version 1 Basic (Column oriented) Choleski



Version 5 Parallel Vector “ Skyline” Choleski Code

“Exactly” same as version 4 , except :

U_{KI}	_____→	$A[\text{MAXA}(I)+I-K]$
U_{KJ}	_____→	$A[\text{MAXA}(J)+J-K]$
U_{IJ}	_____→	$A[\text{MAXA}(J)+J-I]$
S_{IJ}	_____→	$A[\text{MAXA}(J)+J-I]$
U_{II}	_____→	$A[\text{MAXA}(I)]$
U_{II}	_____→	$A[\text{MAXA}(I)]$

Note: In actual coding, the decomposed matrix U will overwrite the original stiffness matrix S. For clarity, however, these 2 matrices have been shown under different names

Forward Substitution

To solve $[U]^T \{y\} = \{F\}$ for $\{y\}$

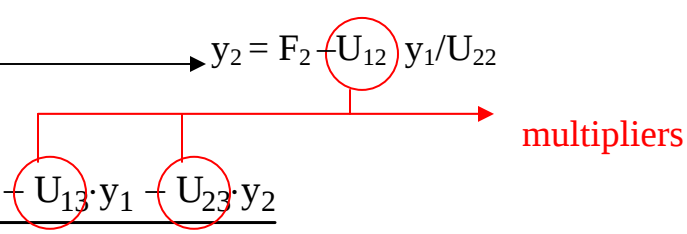
Example :

$$\begin{bmatrix} U_{11} & 0 & 0 \\ U_{12} & U_{22} & 0 \\ U_{13} & U_{23} & U_{33} \end{bmatrix} \begin{Bmatrix} y_1 \\ y_2 \\ y_3 \end{Bmatrix} = \begin{Bmatrix} F_1 \\ F_2 \\ F_3 \end{Bmatrix}$$

$$U_{11}y_1 = F_1 \longrightarrow y_1 = F_1/U_{11}$$

$$U_{12}y_1 + U_{22}y_2 = F_2 \longrightarrow y_2 = F_2 - U_{12}y_1/U_{22}$$

Similarly $y_3 = \frac{F_3 - U_{13}y_1 - U_{23}y_2}{U_{33}}$



multipliers

$$\text{In general : } y_j = \frac{F_j - \sum_{i=1}^{j-1} u_{ij} \cdot y_i}{U_{jj}}$$

Version 1 Basic scheme

```

DO 1 J = 1, NEQ
  Sum1 = 0
  DO 2 I = 1, J-1
2    Sum1 = Sum1 + U(I,J)*y(I)
    y(J) = (y(J) - Sum1)/U(J,J)
1    continue

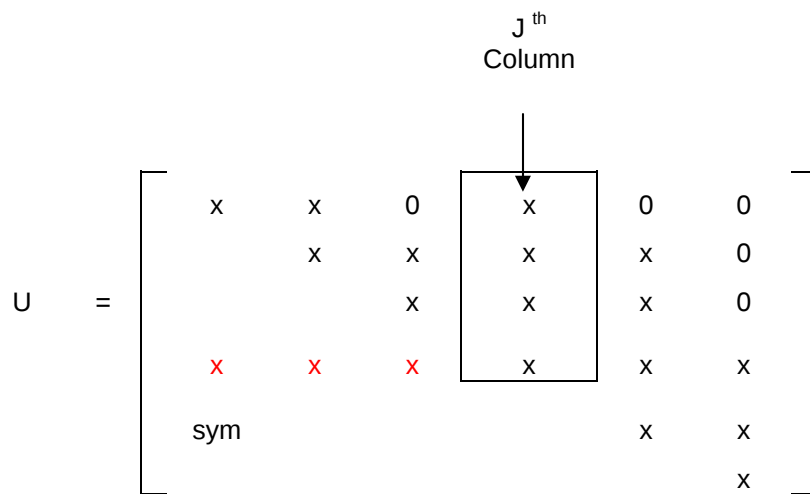
```

Version 2 Skyline scheme

```

DO 1 J= 1, NEQ
  Sum1= 0
c... DO 2 I = Top row of column J, next to diagonal term, +1
      DO 2 I = colh(J), 1 , -1
2    Sum1 = Sum1 + U[MAXA(J)+I]* y (J-I)
1    y(J) = (y(J) - Sum1)/U(MAXA (J))

```



.....

.....

Backward Substitution

To solve $[U]\{Z\} = \{y\}$

Example:

$$\begin{bmatrix} U_{11} & U_{12} & U_{13} & U_{14} \\ 0 & U_{22} & U_{23} & U_{24} \\ 0 & 0 & U_{33} & U_{34} \\ 0 & 0 & 0 & U_{44} \end{bmatrix} \begin{Bmatrix} Z_1 \\ Z_2 \\ Z_3 \\ Z_4 \end{Bmatrix} = \begin{Bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{Bmatrix}$$

$$U_{44} Z_4 = y_4, \text{ hence } Z_4 = \frac{y_4}{U_{44}}$$

$$U_{33} Z_3 + U_{34} Z_4 = y_3, \text{ hence } Z_3 = \frac{y_3 - U_{34} Z_4}{U_{33}}$$

$$\text{Similarly: } Z_2 = \frac{y_2 - U_{23} Z_3 - U_{24} Z_4}{U_{22}}$$

$$Z_1 = \frac{y_1 - U_{12} Z_2 - U_{13} Z_3 - U_{14} Z_4}{U_{11}}$$

$$y_j - \sum_{i=j+1}^{NEQ} U_{ji} Z_i$$

$$\text{In general: } Z_j = \frac{y_j - \sum_{i=j+1}^{NEQ} U_{ji} Z_i}{U_{jj}}$$

Note

Once Z_4 is known, we can update the right hand side vector $\{y\}$ as following:

$$y_3 = y_3 - U_{34} Z_4$$

$$y_2 = y_2 - U_{24} Z_4$$

$$y_1 = y_1 - U_{14} Z_4$$

Version 1 Basic Scheme

In practice, the solution vector $\{Z\}$ will overwrite the right hand side vector $\{y\}$

```
→ DO 1 J = NEQ , 1, -1  (say, J = 4)
   Y(J) = y(J) / U(J,J)
  → Do 2 I = J-1, top row of column J, -1
    →2 y(I) = y(I) - U(I,J)* y(J)
    →1 continue
```

Version 2 Loop Unrolling Scheme

```
→ Do 1 J = NEQ , 1 , -2
   y(J) = y(J)/U(J,J)
   y(J-1) = [ y(J-1)- U(J-1,J) * y(J)] / U(J-1,J-1)
  → Do 2 I = J-colh(J), J-2, +1
    C... Do 2 I = J-1, top row of column J, -1
    →2 y(I) = y(I) - U(I,J) * y(J) - U(I,J-1) * y(J-1)
    →1 continue
```

A.3 LDL^T Algorithm (or U^TDU)

$$\begin{aligned}
 [K] &= \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix} = \left[\begin{bmatrix} 1 & 0 & 0 \\ -\frac{1}{2} & 1 & 0 \\ 0 & -\frac{2}{3} & 1 \end{bmatrix} \cdot \begin{bmatrix} 2 & 0 & 0 \\ 0 & \frac{3}{2} & 0 \\ 0 & 0 & \frac{1}{3} \end{bmatrix} \right] \cdot \begin{bmatrix} 1 & -\frac{1}{2} & 0 \\ 0 & 1 & -\frac{2}{3} \\ 0 & 0 & 1 \end{bmatrix} \\
 &= \begin{bmatrix} 2 & 0 & 0 \\ -1 & \frac{3}{2} & 0 \\ 0 & -1 & \frac{1}{3} \end{bmatrix} \cdot \begin{bmatrix} 1 & -\frac{1}{2} & 0 \\ 0 & 1 & -\frac{2}{3} \\ 0 & 0 & 1 \end{bmatrix}
 \end{aligned}$$

Notes

- (1) LDL^T is essentially the same as the 2nd version (see A.2) of Gauss
- (2) Computer implementation of LDL^T

```

      Do 11 I = 1, N
        Do 22 K = 1, I-1
          xmult=u()/D(I)=u(K,I)/u(K,K)
          {
            Do 33 J = I, N (or I+Irowlength)
              u(I,J) = u(I,J)-xmult*Kth Row
            Continue
          }
          u(K,I) = xmult
        Continue
      Continue
    
```

u(K,J)

For I = 1 → Temporary no change in 1st row
 For I = 2 , Hence K = 1 → 1

$$xmult = \frac{u(1,2)}{u_{11}} = \frac{-1}{2}$$

Loop 33

$\left\{ \begin{array}{l} u_{2,2} = u_{2,2} - (xmult)(u_{1,2}) = 2 - (-1/2)(-1) = 3/2 \\ u_{2,3} = u_{2,3} - (xmult)(u_{1,3}) = -1 - (-1/2)(0) = -1 \end{array} \right.$

$$u(1,2) = xmult = -1/2$$

For I=3 , Hence K= 1 → 2

$$xmult = \frac{u(1,3)}{u_{1,1}} = \frac{0}{2} = 0$$

Loop 33

$\left\{ \begin{array}{l} u_{3,3} = u_{3,3} - (xmult=0)*(u_{1,3}=0) = 1 \end{array} \right.$

$$u(1,3)=0$$

Now K = 2

$$xmult = \frac{u(2,3)}{u_{2,2}} = \frac{-1}{\frac{3}{2}} = \frac{-2}{3}$$

Loop 33

$\left\{ \begin{array}{l} u_{3,3} = u_{3,3} - (xmult = -2/3)(u_{2,3} = -1) = 1/3 \end{array} \right.$

$$u(2,3) = xmult = -2/3$$

----- QED

Hence:

$$U = \begin{pmatrix} 2 & \frac{-1}{2} & 0 \\ \frac{3}{2} & \frac{-2}{3} & \frac{1}{3} \end{pmatrix}$$

$\rightarrow$ [U] matrix, with $U_{ii} = 1$

$\rightarrow$ [L]^T matrix, with $L_{ii} = 1$

$\rightarrow$ [D]

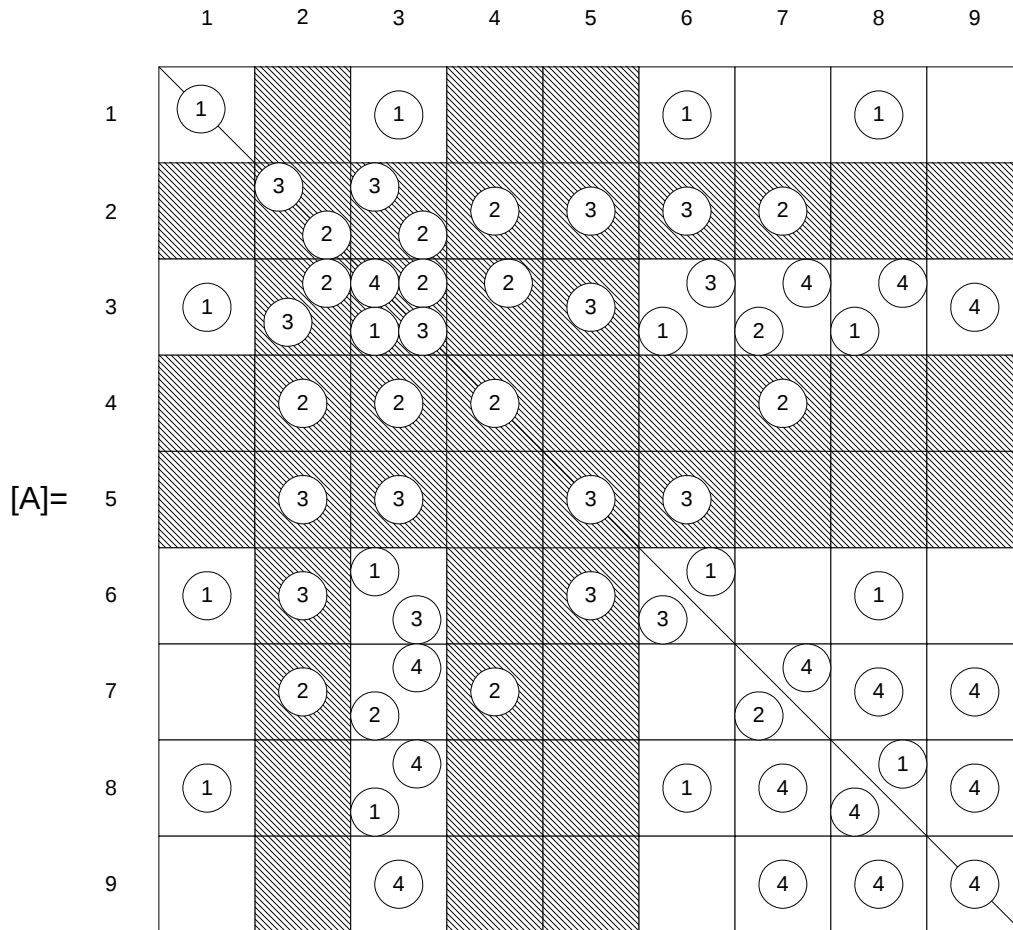


Figure 2 : Total (stiffness) Matrix

IA = 1, 4, 9, 15, 16, 17, 18, 20, 21, 21

JA = 3, 8, 6, 7, 3, 4, 5, 6, 8, 6, 7, 4, 5, 9, 7, 6, 8, 9, 8, 9

Could be
unordered

How to impose (Dirichlet) boundary conditions

Assuming $[A] \vec{x} = \vec{b}$, ndof = 4 and with Dirichlet boundary conditions

$x_2 = k_2$ and $x_3 = k_3$

$$\begin{pmatrix} A_{11} & A_{12} & A_{13} & A_{14} \\ A_{21} & A_{22} & A_{23} & A_{24} \\ A_{31} & A_{32} & A_{33} & A_{34} \\ A_{41} & A_{42} & A_{43} & A_{44} \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 = k_2 \\ X_3 = k_3 \\ X_4 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{pmatrix} \iff \begin{pmatrix} A_{11} & 0 & 0 & A_{14} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ A_{41} & 0 & 0 & A_{44} \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 \\ X_3 \\ X_4 \end{pmatrix} = \begin{pmatrix} b_1 - A_{12} \cdot k_2 - A_{13} \cdot k_3 \\ k_2 \\ k_3 \\ b_4 - A_{42} \cdot k_2 - A_{43} \cdot k_3 \end{pmatrix}$$

Note: After all x_i are found, reactions

$$R_2 = \sum_{j=1}^4 A_{2j} \cdot X_j \quad \text{and} \quad R_3 = \sum_{j=1}^4 A_{3j} \cdot X_j$$