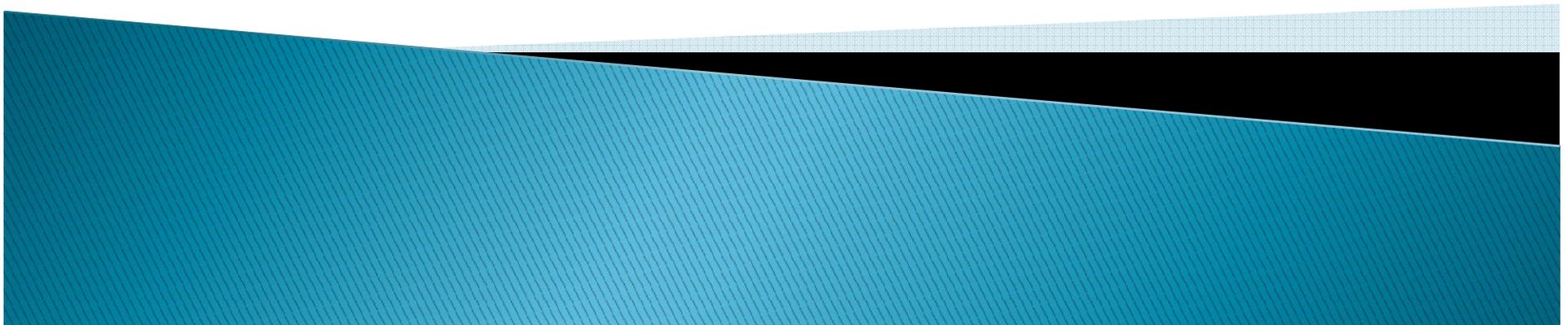


# **Bargain-based Stimulation Mechanism for Selfish Mobile Nodes in Participatory Sensing Network**

Xiaojuan Xie , Haining Chen and Hongyi Wu



# INTRODUCTION

- ▶ This work centers on the Participatory Sensing Network (PSN)
  - PSN consists of mobile devices to enable public and professional users to gather, analyze and share local knowledge
- ▶ Several well-known sensing tasks of PSN

Neighborhood  
Walkability task



Personal Environmental  
Impact Report (PEIR)



Diet Sense task



# INTRODUCTION

- ▶ The participants in PSN can be either voluntary or stimulated by certain reward programs.
  - We focus on the latter in this research
- ▶ The objective of this work is to design an efficient scheme for selfish nodes to maximize their reward.
- ▶ Assumption: node is rational and doesn't cheat

# *Network Architecture*

- ▶ A PSN consists of mobile sensors and sinks
  - Low power radio is employed.
  - The connectivity of PSN is low and intermittent, like the delay tolerant network (DTN).
  - Sinks deliver data to end users.
- ▶ A PSN can support various sensing tasks
  - Each sensing task consists of a sink node and multiple mobile nodes
- ▶ Each task has a unique message type, and its sink node is identified by this message type
  - One mobile node can participate in multiple sensing tasks simultaneously
- ▶ Each data message has two information fields:
  - Message type
  - Message sequence number

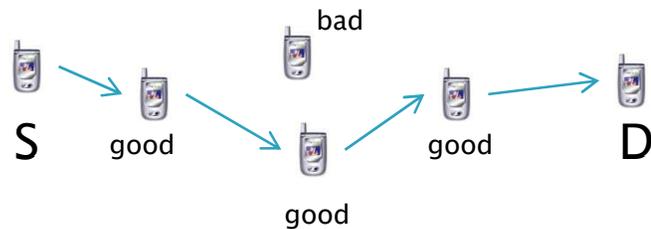
# *Network Architecture*

- ▶ Sink accepts data messages from mobile nodes, if:
  - The message matches sink's type
  - The message sequence number indicated that this message has not been received before
- ▶ sink node rewards the mobile node with one credit unit if it receive one message from mobile node
  - The mobile node that delivers the message to the sink is the only beneficiary of the reward, even it is not the message generator
- ▶ The mobile node has limited buffer size
  - We assume all messages have approximately the same size.
- ▶ Transmission of a message costs one unit of energy.

# Related Work and Challenges

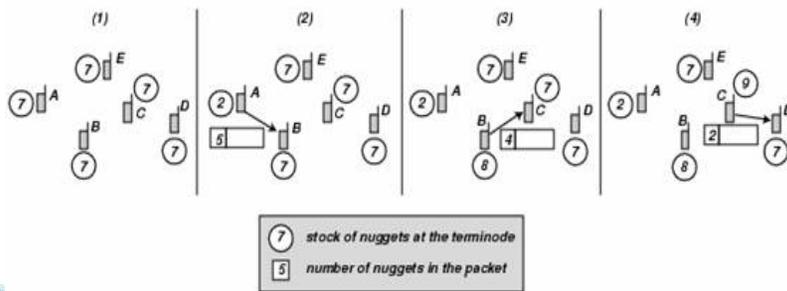
- ▶ Two types of stimulation schemes for selfish ad hoc networks

- Reputation-based scheme

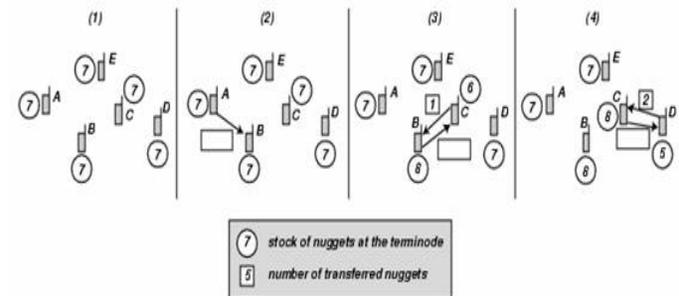


- Credit-based scheme

Packet purse scheme



Packet trade scheme



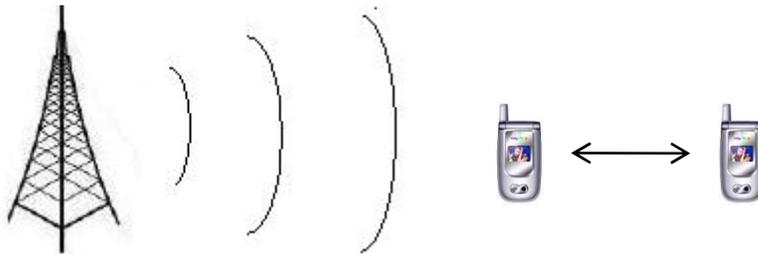
# *Related Work and Challenges*

## ▶ Challenges

- reputation-based scheme
  - Unrealistic for a node to **monitor reputations** of its neighbor nodes due to the intermittent connection
- packet purse approach
  - Difficult for the source node to **estimate the number** of intermediate nodes
- Packet trade approach
  - Intermediate nodes cannot accurately **determine the value** of the data packets since sender usually still keeps a copy of the data in PSN, a DTN-like network

## *Related Work and Challenges*

- ▶ Barter-based stimulation scheme for selfish DTN
  - A stationary source node broadcasts messages without repetition
  - Message types: primary message, secondary message
  - If a node misses any primary message from the source node, it can barter its secondary messages for primary messages with an encountered node
  - Considers **downlink broadcasting** scenario in DTN, instead of the more common scenario of transmissions from various mobile nodes to one or multiple sink nodes



# Contributions

- ▶ A bargain-based stimulation mechanism is proposed for PSN
  - Credit is adopted for stimulating cooperation



- Intermediate nodes exchange messages based on the estimated values of data messages



- A game theory model is developed to address the bargain process

# PRELIMINARIES

  $\mathcal{P}_i(r)$  Node  $i$ 's **contact probability** with the sink node of type  $r$

$$\mathcal{P}_i(r) = \begin{cases} \alpha[\mathcal{P}_i(r)] + (1 - \alpha), & \text{at contact time} \\ \alpha[\mathcal{P}_i(r)], & \text{no contact in } \Delta \end{cases}$$



  $\mathcal{A}_i^m(r)$  **Message appraisal** of message  $m$  ( type  $r$  ) at node  $i$

- Ranges from 0 to 1
- Indicates the probability that nodes except node  $i$  have not delivered any copy of this message  $m$  to the sink node  $r$ .

$$\begin{cases} \mathcal{A}_i^m(r) = [\mathcal{A}_i^m(r)](1 - \mathcal{P}_j(r)) & \text{sender} \\ \mathcal{A}_j^m(r) = [\mathcal{A}_i^m(r)](1 - \mathcal{P}_i(r)) & \text{receiver} \end{cases}$$



  $\mathcal{R}_i^m(r)$  **Expected credit reward** of delivering message  $m$  to type  $r$  sink by node  $i$

$$\mathcal{R}_i^m(r) = \mathcal{A}_i^m(r) \times \mathcal{P}_i(r)$$



# PRELIMINARIES



$\mathcal{S}_i$  **Utility Function** of node i



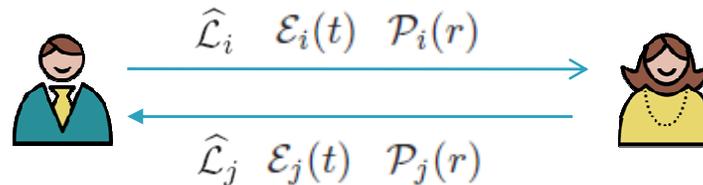
$$\max \mathcal{S}_i = \sum_{r=1}^R \left( \sum_{m \in \phi(r)} \mathcal{R}_i^m(r) - \sum_{m \in \psi(r)} \mathcal{R}_i^m(r) \right)$$

*w.r.t.*  $0 \leq l \leq \mathcal{E}_i(t),$

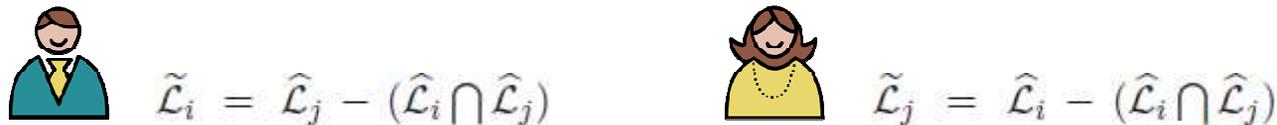
- Node i wants to maximize its utility function should message exchange happen
- R is the total number of message types
- $\phi(r)$  and  $\psi(r)$  are sets of type r messages after and before exchange, respectively
- $l$  is the number of messages sent by node i
- $\mathcal{E}_i(t)$  is the total energy of node i at time t before exchange

# BARGAIN-BASED STIMULATION MECHANISM

- ▶ Exchange control information, including complete list  $\hat{\mathcal{L}}_i, \hat{\mathcal{L}}_j$

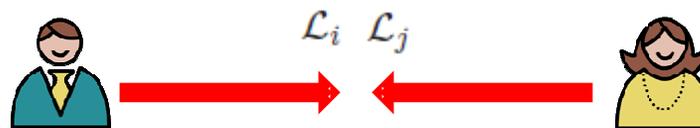


- ▶ Generate candidate list



- Optional action: node  $i$  removes messages of type  $r$  from  $\tilde{\mathcal{L}}_i$  if  $\mathcal{P}_i(r) < \mathcal{P}_j(r)$ ; similarly node  $j$  removes messages of type  $r$  from  $\tilde{\mathcal{L}}_j$  if  $\mathcal{P}_j(r) < \mathcal{P}_i(r)$ .
- With optional action: conservative scheme, O/W: aggressive scheme

- ▶ Bargain process is formulated as two-person cooperative game, the bargain solution (final list  $\mathcal{L}_i, \mathcal{L}_j$ ) is determined by Nash Theorem



# Necessary Condition for Feasible Transaction

- ▶ Theorem 1. *Necessary Condition for Feasible Transaction.* Node  $i$  has a type  $r$  message, and node  $j$  has a type  $s$  message. If both nodes  $i$  and  $j$  find it beneficial to exchange this message pair, then  $\mathcal{P}_i(r) + \mathcal{P}_j(s) < 1$  must be true.
- ▶ Intuitive explanation: two hedgehogs who try to warm each other may hurt each other if they stay too close.



# Scenario 1: Feasible

$$P_i(r)=0.1$$

$$P_i(s)=0.9$$



Type r msg  $[A_i(r)] = 1$   
 $[R_i] = [A_i(r)] * P_i(r) = 0.1$

$$P_j(r)=0.8$$

$$P_j(s)=0.3$$



Type s msg  $[A_j(s)] = 1$   
 $[R_j] = [A_j(s)] * P_j(s) = 0.3$



Exchange



Type r msg  $A_i(r) = [A_i(r)] * (1 - P_j(r)) = 0.2$   
 Type s msg  $A_i(s) = [A_j(s)] * (1 - P_j(s)) = 0.7$   
 $R_i = A_i(r) * P_i(r) + A_i(s) * P_i(s)$   
 $= 0.02 + 0.63 = 0.65$   
 $S_i = R_i - [R_i] = 0.55$



Type s msg  $A_j(r) = [A_j(r)] * (1 - P_i(r)) = 0.9$   
 Type r msg  $A_j(s) = [A_i(s)] * (1 - P_i(s)) = 0.1$   
 $R_j = A_j(s) * P_j(s) + A_j(r) * P_j(r)$   
 $= 0.03 + 0.72 = 0.75$   
 $S_j = R_j - [R_j] = 0.45$

$$P_i(r) + P_j(s) = 0.1 + 0.3 < 1$$



# Scenario 2: Not Feasible

$$P_i(r) = 0.5$$

$$P_i(s) = 0.9$$



Type r msg  $[A_i(r)] = 1$   
 $[R_i] = [A_i(r)] * P_i(r) = 0.5$

$$P_j(r) = 0.8$$

$$P_j(s) = 0.7$$



Type s msg  $[A_j(s)] = 1$   
 $[R_j] = [A_j(s)] * P_j(s) = 0.7$

Exchange



Type r msg  $A_i(r) = [A_i(r)] * (1 - P_j(r)) = 0.2$   
 Type s msg  $A_i(s) = [A_j(s)] * (1 - P_j(s)) = 0.3$   
 $R_i = A_i(r) * P_i(r) + A_i(s) * P_i(s)$   
 $= 0.01 + 0.27 = 0.28$   
 $S_i = R_i - [R_i] = -0.22$



Type s msg  $A_j(r) = [A_j(r)] * (1 - P_i(r)) = 0.5$   
 Type r msg  $A_j(s) = [A_i(s)] * (1 - P_i(s)) = 0.1$   
 $R_j = A_j(s) * P_j(s) + A_j(r) * P_j(r)$   
 $= 0.4 + 0.07 = 0.47$   
 $S_j = R_j - [R_j] = -0.23$

$$P_i(r) + P_j(s) = 0.5 + 0.7 > 1$$



# GAME THEORY MODEL FOR BARGAIN PROCESS

## ▶ Two-Person Cooperative Games

- Consists of two rational and selfish players that cooperate with each other but have conflict interests
- Two players reach binding agreement which benefits both persons



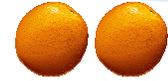
# Nash Theorem

- ▶ The solution for two-person cooperative game, which satisfies four axioms: invariance, symmetry, independence and Pareto optimality, is given by

$$(\hat{s}_1, \hat{s}_2) = \arg \max_{(s_1, s_2) \in \mathcal{S}} (s_1 - d_1) \times (s_2 - d_2)$$

$(s_1, s_2)$  forms utility gain space  $\mathcal{S}$ ;  $(d_1, d_2)$  is the status quo point in space  $\mathcal{S}$ , usually defined as the utility gain of no cooperation

# Nash Theorem: A Simple Example

	Babara	Don	$s_1$	$s_1 - d_1$	$s_2$	$s_2 - d_2$	$(s_1 - d_1) * (s_2 - d_2)$
Before Bargaining			10	0	15	0	0
Bargaining Outcome			14	4	25	10	40
			12	2	11	-4	-8
			4	-6	36	21	-126
			6	-4	35	20	-80
			16	6	8	-7	-42
			20	10	10	-5	-50
		Null	21	11	5	-10	-110
	Null		0	-10	37	22	-220

# Greedy Algorithm for Game Solution

- ▶ Nash Theorem points out what the optimal solution is, but does not show how to reach the optimal solution.
- ▶ A greedy algorithm is proposed to divide bargain process into a finite sequence of steps, and each step corresponds to the exchange of a message pair between nodes  $i$  and  $j$ .
  - Unrealistic to adopt the brute forth manner to deplete all the possible patterns looking for Nash Solution due to the exponential complexity
- ▶ Nash product table

NASH PRODUCT OF MESSAGE PAIR

		$\tilde{\mathcal{L}}_j$			
		$a_1$	$a_2$	...	$a_N$
$\tilde{\mathcal{L}}_i$	$b_1$	$S_i^{1,1} \times S_j^{1,1}$	$S_i^{1,2} \times S_j^{2,1}$	...	$S_i^{1,N} \times S_j^{N,1}$
	$b_2$	$S_i^{2,1} \times S_j^{1,2}$	$S_i^{2,2} \times S_j^{2,2}$	...	$S_i^{2,N} \times S_j^{N,2}$
	...	...	...	...	...
	$b_M$	$S_i^{M,1} \times S_j^{1,M}$	$S_i^{M,2} \times S_j^{2,M}$	...	$S_i^{M,N} \times S_j^{N,M}$

$$\left\{ \begin{array}{l} C_i^{b_m} = \mathcal{R}_i^{b_m}(T^{b_m}), \quad D_i^{a_n} = [\mathcal{R}_i^{a_n}(T^{a_n})] - \mathcal{R}_i^{a_n}(T^{a_n}) \\ S_i^{m,n} = C_i^{b_m} - D_i^{a_n} \\ C_j^{a_n} = \mathcal{R}_j^{a_n}(T^{a_n}), \quad D_j^{b_m} = [\mathcal{R}_j^{b_m}(T^{b_m})] - \mathcal{R}_j^{b_m}(T^{b_m}) \\ S_j^{n,m} = C_j^{a_n} - D_j^{b_m}, \end{array} \right.$$

where  $C, D, S$  stand for credit, debit, utility gain

# Greedy Algorithm for Game Solution

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**Algorithm 1** Greedy Algorithm for Game Solution.

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- 1: Set final list  $\mathcal{L}_i = \mathcal{L}_j = \emptyset$  and  $l = 0$ ;
  - 2: In Nash product table,  $a_n$  and  $b_m$  are chosen with  
max positive Nash product. If fail, go to step 11;
  - 3: **if**  $(\mathcal{E}_i, \mathcal{E}_j \geq l + 1)$  and  $(B_i(S_i^{m,n}), B_j(S_j^{n,m}) \geq 1)$  **then**
  - 4:    $\mathcal{L}_i = \mathcal{L}_i \cup b_m$ ;
  - 5:    $\mathcal{L}_j = \mathcal{L}_j \cup a_n$ ;
  - 6:    $l++$ ;  $\mathcal{E}_i--$ , and  $\mathcal{E}_j--$ ;
  - 7: **else**
  - 8:   Go to step 11;
  - 9: **end if**
  - 10: Remove column of  $a_n$  and row of  $b_m$ , go to step 2;
  - 11: Terminate.
- 

$B_i(x)$  denotes the number of messages in node  $i$  with credit value less than  $x$ . Message  $a_n$  and  $b_m$  can be exchanged only when  $B_i(S_i^{m,n}) \geq 1$  and  $B_j(S_j^{n,m}) \geq 1$

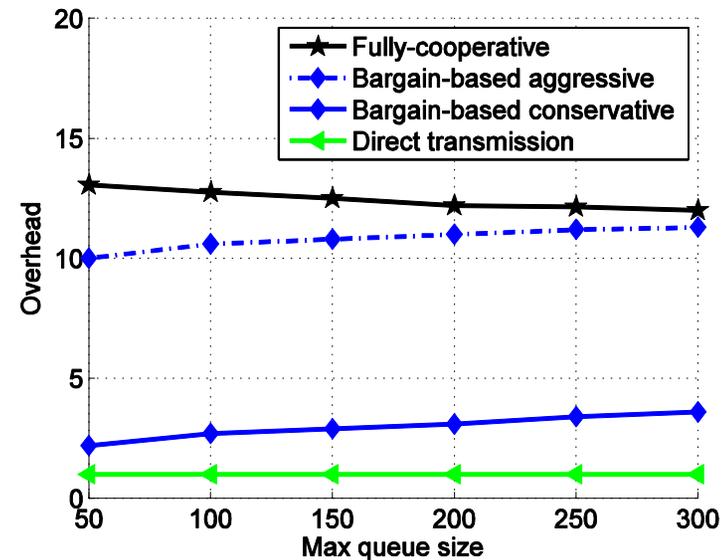
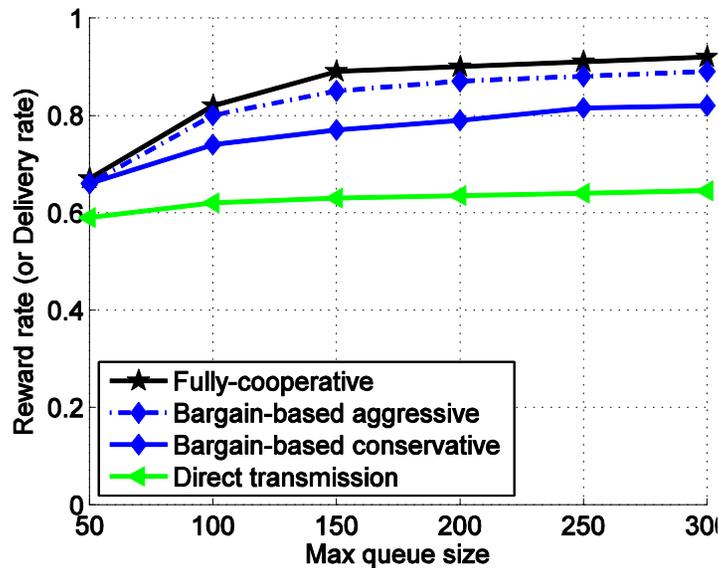
# Simulation

- ▶ Our simulations are based on real mobility traces available at CRAWDAD
- ▶ Two type of trace data
  - Position-based trace
    - Record GPS positions of nodes at fixed time intervals
  - Contact-based trace
    - No position info, only contact information
- ▶ Performance Metrics
  - Reward rate ( delivery rate)
  - Network overhead
  - Fairness  $f(x_1, x_2, \dots, x_n) = \frac{(\sum_{i=1}^n x_i)^2}{n \sum_{i=1}^n x_i^2}$ ,  $x_i$  : node  $i$ 's overhead
- ▶ We compare our work with direct transmission and fully-cooperative scheme in DTN<sup>[1]</sup>.

[1]Y. Wang and H. Wu, "DFT-MSN: The Delay Fault Tolerant Mobile Sensor Network for Pervasive Information Gathering," in Proc. of IEEE Conference on Computer Communications (INFOCOM), 2006, pp. 1-12

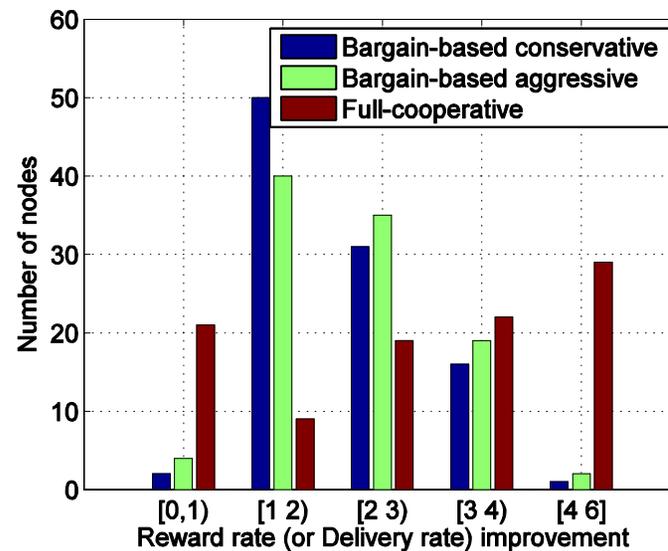
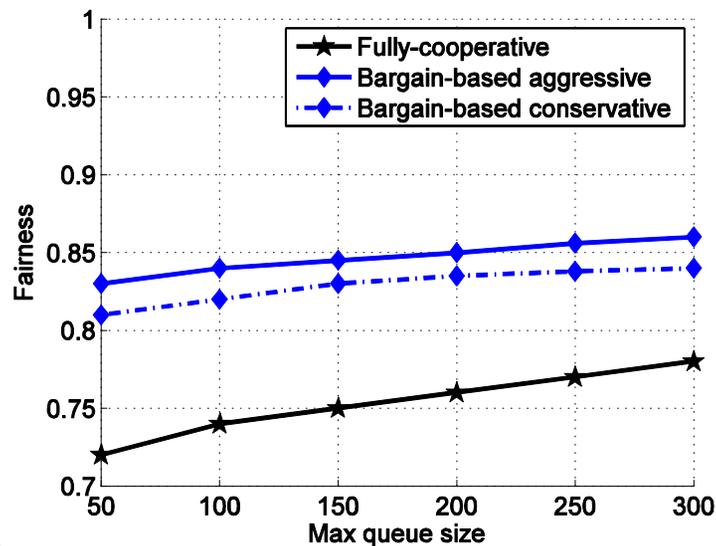
# Position-based trace

- ▶ Trace data of ZebraNet project is used in our simulations.
- ▶ Bargain-based scheme is effective in promoting nodal cooperation and improving network throughput.
  - The aggressive scheme is only 3% less than fully cooperative scheme in reward rate, while the conservative scheme is 10% less.
  - The overhead of bargain-based scheme is less than fully-cooperative scheme



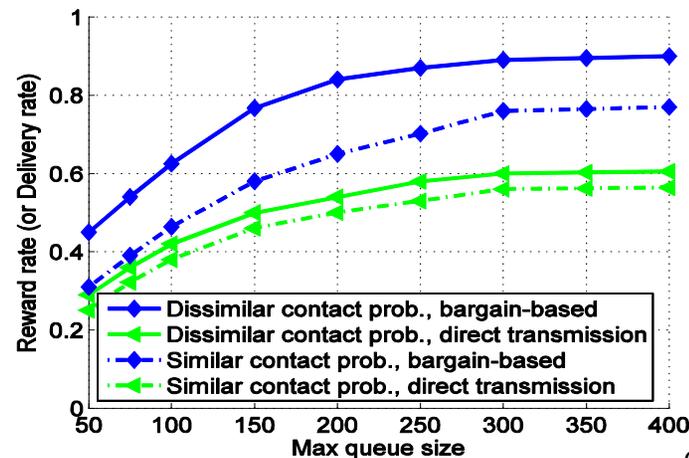
# Position-based trace

- ▶ Bargain-based schemes have much better fairness than fully-cooperative scheme
  - Bargain process allows each node to balance its individual interest with its contribution to network.
  - Compared to direct transmission, fully-cooperative scheme has more than 20% nodes experience worse performance, while 95% nodes enjoy more rewards under both aggressive and conservative scheme.



# Contact-based trace

- ▶ Trace data of Cambridge Huggle project is used
  - In Huggle project, mobile nodes called iMotes were distributed to 50 people attending IEEE InfoCom workshop during three days.
  - 2 sinks and 2 message types
- ▶ Similar contact probability vs dissimilar contact probability
  - ▶ Similar contact probability: all nodes have  $P_i[1]$ ,  $P_i[2]$  uniformly distributed in  $[0, 1]$
  - ▶ Dissimilar contact probability: half of nodes have  $P_i[1]$ ,  $P_i[2]$  uniformly distributed in  $[0, 0.4]$ ,  $[0.6, 1]$ , the other half of nodes have  $P_i[1]$ ,  $P_i[2]$  uniformly distributed in  $[0.6, 1]$ ,  $[0, 0.4]$
- ▶ Bargain-based mechanism achieves more gain when nodes have complementary sets of contact probabilities
  - Reward rate enhancement is 50% in scenario of dissimilar contact probability, compared to 35% enhancement in scenario of similar contact probability



# Conclusion

- ▶ A novel bargain-based stimulation mechanism is proposed to encourage cooperation in selfish participatory sensing networks.
- ▶ The paper reveals necessary condition for feasible transaction of message exchange.
- ▶ The final message exchange list is determined in a bargain process, which is formulated as a two-person cooperative game.
- ▶ A greedy algorithm is proposed to resolve the game and find out optimal solution.
- ▶ The results show that our bargain-based stimulation schemes are fair and have comparable performance with fully-cooperative scheme with less overhead.

