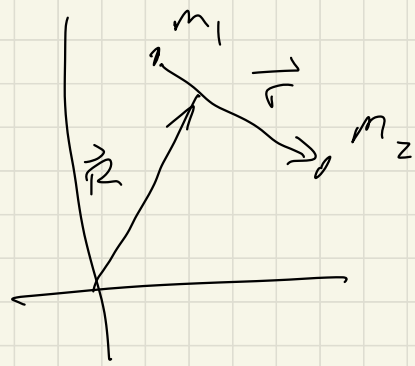



2 body $\rightarrow$ 1 body

$$U = U(\{\vec{r}\}, \{\dot{\vec{r}}\}, \dots)$$

$$U \neq U(\vec{R})$$

$$\vec{R} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2}{m_1 + m_2}$$



$$\vec{r} = \vec{r}_2 - \vec{r}_1$$

$$\mu = \frac{m_1 m_2}{m_1 + m_2}$$

$\vec{R}$ is cyclic

$\vec{P}$ conserved

CHOOSE A REFERENCE FRAME
WHERE $\vec{P} = M \dot{\vec{R}} = 0$

CONSERVATIVE CENTRAL FORCE

$$V = V(r) \quad \vec{F} = -\frac{\partial V}{\partial r} \hat{r}$$

SPHERICALLY SYMMETRIC

ANY ROTATION LEAVES THE E.O.M.

UNCHANGED $\Rightarrow$ CONSERVED
QUANTITIES

$$\vec{L} = \vec{r} \times \vec{p} \text{ CONSERVED}$$

$\Rightarrow \vec{r}$ IN A PLANE $\perp$ TO $\vec{L}$ $\exists$ CONSTRAINTS

SPECIAL CASE $L = 0$

$\vec{r} \parallel \vec{p}$ STRAIGHT LINE
MOTION

CHOOSE $\hat{z} \parallel \vec{L} \Rightarrow \phi = \pi/2$

NOTATION

(r, θ, ϕ)

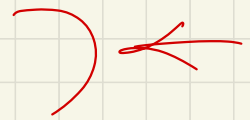
$$z = r \cos \theta$$

$$x = r \sin \theta \cos \phi$$

(r, ϕ, θ)

$$z = r \cos \phi$$

$$x = r \sin \phi \cos \theta$$



ALL MOTION IS IN $x-y$ PLANE

$$\mathcal{L} = T - V$$

$$= \frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\theta}^2) - V(r)$$

θ CYCLIC

$$P_{\theta} = \frac{\partial \mathcal{L}}{\partial \dot{\theta}} = \mu r^2 \dot{\theta} \equiv l_z$$

ALTERNATIVELY $V = V(r)$ CENTRAL

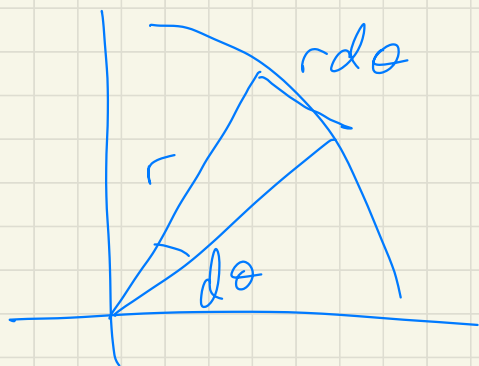
$\Rightarrow$ MOTION IS PLANAR

AREA SWEEP

$$dA = r^2 d\theta \frac{1}{2}$$

AREAL VELOCITY

$$\frac{dA}{dt} = \frac{1}{2} r^2 \dot{\theta}$$



CONSERVATION OF $P_{\theta} \Leftrightarrow$ CONSTANT

AREAL VELOCITY

KEPLER'S 2ND LAW

$$P_\theta = \mu r^2 \dot{\theta} = \mu |\vec{r} \times \dot{\vec{r}}| = l_z$$

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{r}} - \frac{\partial \mathcal{L}}{\partial r} = \mu \ddot{r} - \mu r \dot{\theta}^2 + \frac{\partial V}{\partial r} = 0$$

$$\mu \ddot{r} - \mu r \dot{\theta}^2 = f(r)$$

$$\mu \ddot{r} - \frac{l_z^2}{\mu r^3} = f(r) \quad \text{FORCE}$$

① $V \neq V(t) \Rightarrow E$ conserved

$$E = \frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\theta}^2) + V(r)$$

② $\mu \ddot{r} = \frac{l_z^2}{\mu r^3} + f(r)$

$$= - \frac{d}{dr} \left(V + \frac{1}{2} \frac{l_z^2}{\mu r^2} \right)$$

multiply both sides by $\dot{r}$

LHS: $\mu \ddot{r} \dot{r} = \frac{d}{dt} \left(\frac{1}{2} \mu \dot{r}^2 \right)$

RHS: $-\frac{d}{dr} () \frac{dr}{dt} = -\frac{d}{dt} ()$

$$\frac{d}{dt} \left(\frac{1}{2} \mu \dot{r}^2 \right) = - \frac{d}{dt} \left(V + \frac{1}{2} \frac{l_z^2}{\mu r^2} \right)$$

$$\frac{d}{dt} \left(\frac{1}{2} \mu \dot{r}^2 + \frac{1}{2} \frac{l_z^2}{\mu r^2} + V \right) = 0$$

E CONSERVED

$$\textcircled{3} \quad h = \sum_i p_i \dot{q}_i - 2$$

$$= (\mu \dot{r}) \dot{r} + \mu r^2 \dot{\theta}^2 - \left[\frac{\mu}{2} (\dot{r}^2 + r^2 \dot{\theta}^2) - V \right]$$

$$E = h = \frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\theta}^2) + V$$

$$\text{Solve } \dot{r} = \left[\frac{2}{\mu} \left(E - V - \frac{l_z^2}{2\mu r^2} \right) \right]^{1/2}$$

$$t = \int_{r_0}^r \frac{dr}{\sqrt{\quad}} \Rightarrow t(r)$$

invert to get $r(t)$

Solved!

Orbits

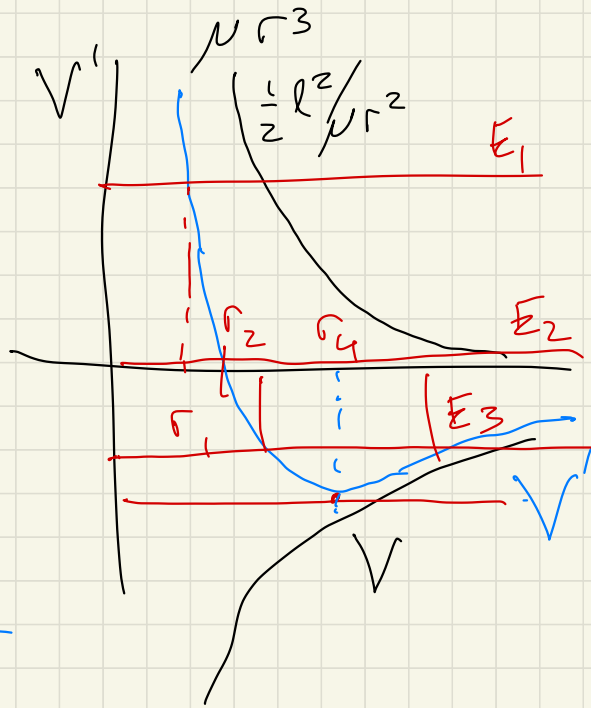
$$f' = f + \frac{l^2}{\mu r^3}$$

$$V' = V + \frac{1}{2} \frac{l^2}{\mu r^2}$$

$$E = V' + \frac{1}{2} \mu \dot{r}^2$$

$|V|$ decreases
slower than $1/r^2$
as $r \rightarrow \infty$

$|V|$ increases slower
than $1/r^2$ as
 $r \rightarrow 0$



① $E_1 > 0 \quad r > r_1$
 $\frac{1}{2} \mu \dot{r}^2 = E_1$ ② $r \rightarrow \infty$

② $E_2 = 0 \quad r > r_2$

$$\frac{1}{2} \mu \dot{r}^2 = 0$$

If $V \sim -\frac{k}{r}$ parabola

(If $V \sim -k/r$ hyperbola)

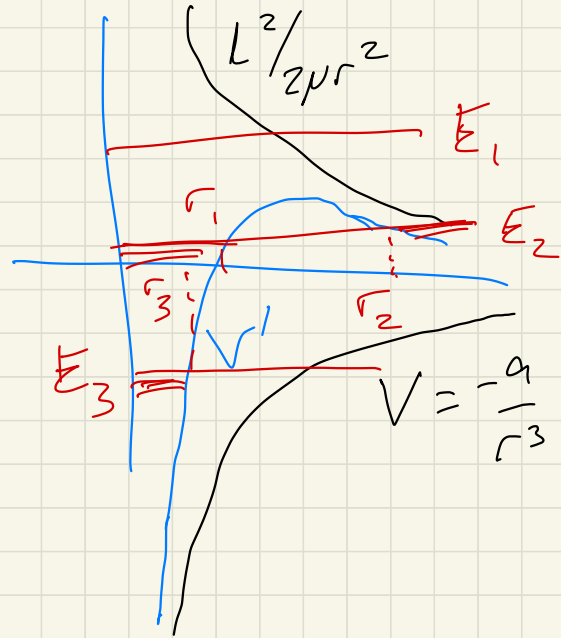
③ $E_3 < 0 \quad r_3^{\min} < r < r_3^{\max}$

ORBIT BOUNDED
CLOSED?

④ $E_4 = V'_{\min} \quad \underline{r = r_4}$
CIRCLE

If $V \sim -\frac{k}{r}$, ellipse

FAILS THE LIMITS



$$V(r) = -\frac{a}{r^3}$$

① $E_1 > V$ $\forall r$
 r unbounded

② $E_2 > 0$

EITHER $r < r_1$
 OR $r > r_2$

③ $E_3 < 0$
 $r < r_3$

ISOTROPIC HARMONIC OSCILLATOR

$$f = -kr \quad V = \frac{1}{2}kr^2$$

a) $l=0 \Rightarrow 1D \text{ H.O.}$

$$V' = V$$

b) $l \neq 0$

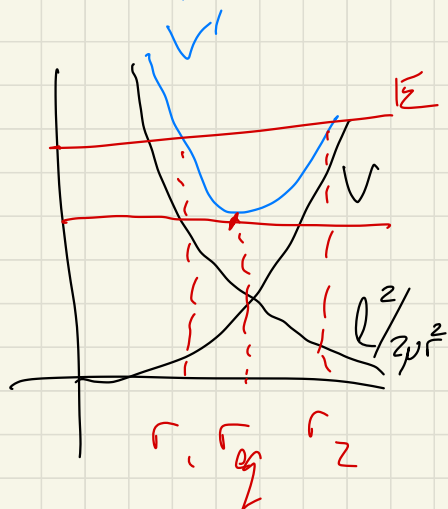
$$V' = \frac{l^2}{2\mu r^2} + \frac{k}{2}r^2$$

EQUILIBRIUM $0 = \frac{\partial V'}{\partial r} = \frac{-l^2}{\mu r^3} + kr$

$$r_{eq}^4 = \frac{l^2}{\mu k}$$

$$V'_{eq} = \frac{l^2}{2\mu l / \sqrt{\mu k}} + \frac{k}{2} \frac{l}{\sqrt{\mu k}} = l \sqrt{\frac{k}{\mu}} = l\omega$$

$$T'_{eq} = \frac{1}{2} m \dot{r}^2 = 0$$



PERIOD (USE AREA)

$$l = \sqrt{\mu k} r_{eq}^2$$

$$\frac{dA}{dt} = \frac{1}{2} r^2 \dot{\theta} = \frac{l}{2\pi}$$

$$\text{PERIOD} = \frac{\text{AREA}}{\text{RATE}} = \frac{A}{dA/dt} = \frac{\pi r_{eq}^2}{l/2\pi}$$

$$= 2\pi \mu r_{eq}^2 / l$$

$$= \frac{2\pi \mu r_{eq}^2}{\sqrt{\mu k} r_{eq}^2} = 2\pi \sqrt{\frac{\mu}{k}} = \frac{2\pi}{\omega}$$

$$\text{CARTESIAN } \mathcal{L} = \frac{1}{2} \mu (\dot{x}^2 + \dot{y}^2) + \frac{k}{2} (x^2 + y^2)$$

$$x = A_x \cos(\omega t + \phi_x) \quad y = A_y \sin(\omega t + \phi_y)$$

$$\text{AT EQUIL: } A_x = A_y \quad \phi_x = \phi_y$$

SMALL OSCILLATIONS AROUND r_{eq}

$$V'(r) = V'(r_{eq}) + \cancel{\frac{2V'}{2r}} \delta r + \frac{1}{2} \left. \frac{d^2 V'}{dr^2} \right|_{r_{eq}} \delta r^2$$

$$= C + \frac{1}{2} \left(\frac{3l^2}{\mu r_{eq}^4} + k \right) \delta r^2$$

$$= C + \frac{1}{2} (4k) (\delta r)^2$$

$$l^2 = \mu k r_{eq}^4$$

$$\omega_{osc} = \sqrt{\frac{k'}{\mu}} = \sqrt{\frac{4k}{\mu}} = 2\omega$$

CLOSED ORBIT

BECAUSE Z IS

RATIONAL

TURNING POINTS (min, max r)

$$E = \frac{l^2}{2\mu r^2} + \frac{k}{2} r^2 + \cancel{\frac{1}{2}\mu \dot{r}^2} \quad 0$$

$$\dot{r} = 0 \text{ FOR}$$

EXTREME r

$$\frac{k}{2} r^4 - E r^2 + \frac{l^2}{2\mu} = 0$$

$$r^4 - \frac{2E}{k} r^2 + \frac{l^2}{\mu k} = 0$$

$$r_{\max}^2 = \left(\frac{\cancel{2}E}{k} \pm \left[\frac{\cancel{4}E^2}{k^2} - \frac{\cancel{4}l^2}{\mu^2 k^2} \right]^{1/2} \right)$$

$$\cancel{2}$$